GD25Q127C

GD25Q127C

DATASHEET



GD25Q127C

Contents

1. FE	EATURES	4
2. GE	ENERAL DESCRIPTION	5
3. ME	EMORY ORGANIZATION	8
	EVICE OPERATION	
	ATA PROTECTION	
6. ST	TATUS REGISTER	13
7. CC	OMMANDS DESCRIPTION	15
7.1.	Write Enable (WREN) (06H)	18
7.2.	WRITE DISABLE (WRDI) (04H)	
7.3.	Write Enable for Volatile Status Register (50H)	
7.4.	READ STATUS REGISTER (RDSR) (05H OR 35HOR 15H)	
7.5.	WRITE STATUS REGISTER (WRSR) (01H or 31Hor 11H)	
7.6.	READ DATA BYTES (READ) (03H)	
7.7.	READ DATA BYTES AT HIGHER SPEED (FAST READ) (0BH)	
7.8.	DUAL OUTPUT FAST READ (3BH)	
7.9.	QUAD OUTPUT FAST READ (6BH)	
7.10.	DUAL I/O FAST READ (BBH).	
7.11.	QUAD I/O FAST READ (EBH).	23
7.12.	QUAD I/O WORD FAST READ (E7H)	25
7.13.	SET BURST WITH WRAP (77H)	26
7.14.	PAGE PROGRAM (PP) (02H)	27
7.15.	QUAD PAGE PROGRAM (32H)	27
7.16.	SECTOR ERASE (SE) (20H)	28
7.17.	32KB BLOCK ERASE (BE) (52H)	29
7.18.	64KB BLOCK ERASE (BE) (D8H)	29
7.19.	CHIP ERASE (CE) (60/C7H)	30
7.20.	DEEP POWER-DOWN (DP) (B9H)	30
7.21.	RELEASE FROM DEEP POWER-DOWN AND READ DEVICE ID (RDI) (ABH)	31
7.22.	READ MANUFACTURE ID/ DEVICE ID (REMS) (90H)	32
7.23.	READ MANUFACTURE ID/ DEVICE ID DUAL I/O (92H)	32
7.24.	READ MANUFACTURE ID/ DEVICE ID QUAD I/O (94H)	
7.25.	READ IDENTIFICATION (RDID) (9FH)	34
7.26.	PROGRAM/ERASE SUSPEND (PES) (75H)	35
7.27.	PROGRAM/ERASE RESUME (PER) (7AH)	36
7.28.	Erase Security Registers (44H)	36
7.29.	PROGRAM SECURITY REGISTERS (42H)	37
7.30.	READ SECURITY REGISTERS (48H).	38
7.31.	ENABLE RESET (66H) AND RESET (99H)	38
7.32.	READ UNIQUE ID (4BH)	39



GD25Q127C

7.33.	READ SERIAL FLASH DISCOVERABLE PARAMETER (5AH)	40
8. EL	ECTRICAL CHARACTERISTICS	45
8.1.	POWER-ON TIMING	45
8.2.	INITIAL DELIVERY STATE	45
8.3.	ABSOLUTE MAXIMUM RATINGS	45
8.4.	CAPACITANCE MEASUREMENT CONDITIONS	46
8.5.	DC CHARACTERISTICS	47
8.6.	AC CHARACTERISTICS	53
9. OF	RDERING INFORMATION	67
9.1.	VALID PART NUMBERS	68
10 .	PACKAGE INFORMATION	70
10.1.	PACKAGE SOP8 208MIL	70
10.2.	PACKAGE VSOP8 208MIL	71
10.3.	PACKAGE DIP8 300MIL	72
10.4.	PACKAGE SOP16 300MIL	73
10.5.	PACKAGE WSON8 (6*5MM)	74
10.6.	PACKAGE WSON8 (8*6MM)	75
10.7.	PACKAGE TFBGA-24BALL (6*4 BALL ARRAY)	76
44	DEVICION HISTORY	77



GD25Q127C

1. FEATURES

- ◆ 128M-bit Serial Flash
 - -16384K-byte
 - -256 bytes per programmable page
- Standard, Dual, Quad SPI
 - -Standard SPI: SCLK, CS#, SI, SO, WP#, HOLD#/ RESET#
 - -Dual SPI: SCLK, CS#, IO0, IO1, WP#, HOLD#/ RESET#
 - -Quad SPI: SCLK, CS#, IO0, IO1, IO2, IO3
- ♦ High Speed Clock Frequency
 - -104MHz for Standard and Dual SPI fast read with 30PF load ◆ Low Power Consumption
 - -Dual I/O Data transfer up to 208Mbits/s
 - -Quad I/O Data transfer up to 416Mbits/s
- ◆ Software/Hardware Write Protection
 - -Write protect all/portion of memory via software
 - -Enable/Disable protection with WP# Pin
 - -Top/Bottom Block protection
- ◆ Allows XIP (execute in place) Operation
 - -Continuous Read With 8/16/32/64-byte Wrap
- ◆ Minimum 100,000 Program/Erase Cycles
- ◆ Data Retention
 - -20-year data retention typical

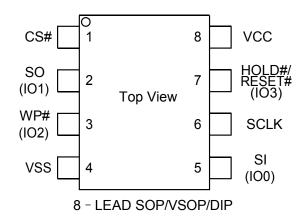
- ◆ Fast Program/Erase Speed
 - -Page Program time: 0.5ms typical
 - -Sector Erase time: 50ms typical
 - -Block Erase time: 0.16/0.3s typical
 - -Chip Erase time: 50s typical
- ◆ Flexible Architecture
 - -Uniform Sector of 4K-byte
 - -Uniform Block of 32/64K-byte
- - -20µA typical standby current
 - -1µA typical power down current
- Advanced Security Features
 - -128-bit Unique ID for each device
 - -3x1024-Byte Security Registers With OTP Locks
 - -Discoverable parameters (SFDP) register
- ◆ Single Power Supply Voltage
 - -Full voltage range: 2.7~3.6V
- Package Information
 - -SOP8 (208mil)
 - -VSOP8 (208mil)
 - -SOP16 (300mil)
 - -DIP8 (300mil)
 - -WSON8 (8*6mm)
 - -WSON8 (6*5mm)
 - -TFBGA-24 (6*4 ball array)

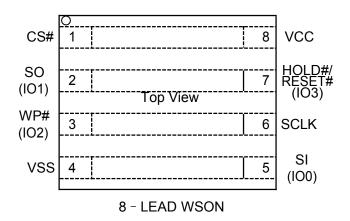
GD25Q127C

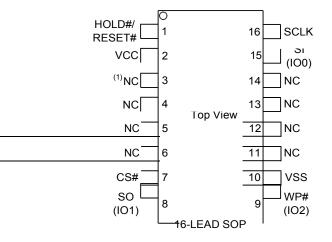
2. GENERAL DESCRIPTION

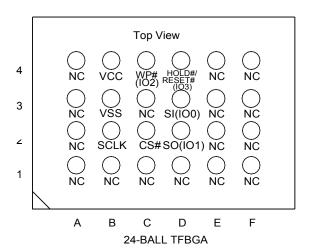
The GD25Q127C (128M-bit) Serial flash supports the standard Serial Peripheral Interface (SPI), and supports the Dual/Quad SPI: Serial Clock, Chip Select, Serial Data I/O0 (SI), I/O1 (SO), I/O2 (WP#), and I/O3 (HOLD#/ RESET#). The Dual I/O data is transferred with speed of 208Mbits/s and the Quad I/O & Quad output data is transferred with speed of 416Mbits/s.

CONNECTION DIAGRAM









Note:

(1) Only for special order, Pin 3 of 16-LEAD SOP package is RESET# pin. Please contact GigaDevice for detail.



GD25Q127C

PIN DESCRIPTION

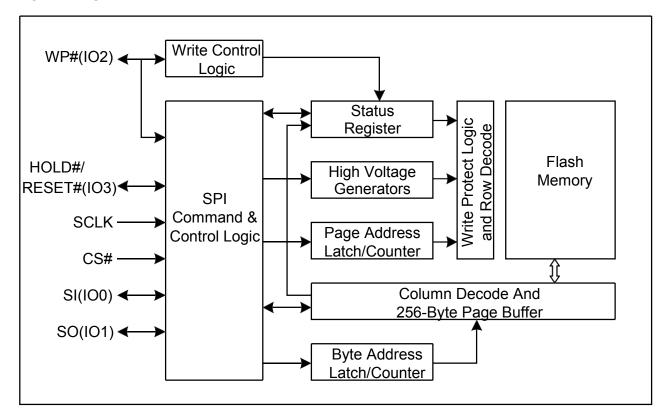
Pin Name	I/O	Description
CS#	I	Chip Select Input
SO (IO1)	I/O	Data Output (Data Input Output 1)
WP# (IO2)	I/O	Write Protect Input (Data Input Output 2)
vss		Ground
SI (IO0)	I/O	Data Input (Data Input Output 0)
SCLK	I	Serial Clock Input
HOLD#/RESET# (IO3)	I/O	Hold or Reset Input (Data Input Output 3)
VCC		Power Supply

Note: CS# must be driven high if chip is not selected. Please don't leave CS# floating any time after power is on.



GD25Q127C

BLOCK DIAGRAM



GD25Q127C

3. MEMORY ORGANIZATION

GD25Q127C

Each device has	Each block has	Each sector has	Each page has	
16M	64/32K	4K	256	bytes
64K	256/128	16	-	pages
4096	16/8	-	-	sectors
256/512	-	-	-	blocks

UNIFORM BLOCK SECTOR ARCHITECTURE

GD25Q127C 64K Bytes Block Sector Architecture

Block	Sector	Address range		
	4095	FFF000H	FFFFFH	
255				
	4080	FF0000H	FF0FFFH	
	4079	FEF000H	FEFFFFH	
254				
	4064	FE0000H	FE0FFFH	
	47	02F000H	02FFFFH	
2				
	32	020000H	020FFFH	
	31	01F000H	01FFFFH	
1				
	16	010000H	010FFFH	
	15	00F000H	00FFFFH	
0				
	0	000000H	000FFFH	



GD25Q127C

4. DEVICE OPERATION

SPI Mode

Standard SPI

The GD25Q127C features a serial peripheral interface on 4 signals bus: Serial Clock (SCLK), Chip Select (CS#), Serial Data Input (SI) and Serial Data Output (SO). Both SPI bus mode 0 and 3 are supported. Input data is latched on the rising edge of SCLK and data shifts out on the falling edge of SCLK.

Dual SPI

The GD25Q127C supports Dual SPI operation when using the "Dual Output Fast Read" and "Dual I/O Fast Read" (3BH and BBH) commands. These commands allow data to be transferred to or from the device at twice the rate of the standard SPI. When using the Dual SPI command the SI and SO pins become bidirectional I/O pins: IO0 and IO1.

Quad SPI

The GD25Q127C supports Quad SPI operation when using the "Quad Output Fast Read"," Quad I/O Fast Read", "Quad I/O Fast Read", "Quad I/O Word Fast Read" (6BH,EBH,E7H) commands. These commands allow data to be transferred to or from the device at four times the rate of the standard SPI. When using the Quad SPI command the SI and SO pins become bidirectional I/O pins: IOO and IO1, and WP# and HOLD#/RESET# pins become IO2 and IO3. Quad SPI commands require the non-volatile Quad Enable bit(QE) in Status Register to be set.

Hold

The HOLD/RST bit is used to determine whether HOLD# or RESET# function should be implemented on the hardware pin for 8-pin packages. When HOLD/RST=0, the pin7 acts as HOLD#, the HOLD# function is only available when QE=0, If QE=1, The HOLD# functions is disabled, the pin acts as dedicated data I/O pin.

The HOLD# signal goes low to stop any serial communications with the device, but doesn't stop the operation of write status register, programming, or erasing in progress.

The operation of HOLD, need CS# keep low, and starts on falling edge of the HOLD# signal, with SCLK signal being low (if SCLK is not being low, HOLD operation will not start until SCLK being low). The HOLD condition ends on rising edge of HOLD# signal with SCLK being low (If SCLK is not being low, HOLD operation will not end until SCLK being low).

The SO is high impedance, both SI and SCLK don't care during the HOLD operation, if CS# drives high during HOLD operation, it will reset the internal logic of the device. To re-start communication with chip, the HOLD# must be at high and then CS# must be at low.

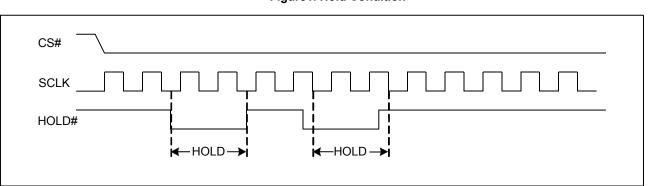


Figure 1. Hold Condition



GD25Q127C

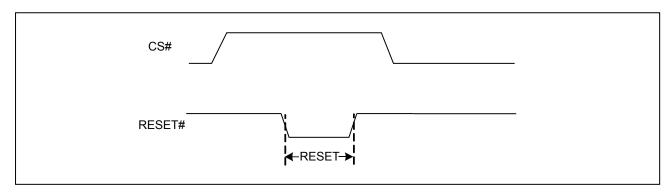
RESET

The RESET# pin allows the device to be reset by the control. For the WSON8 package, the pin7 can be configured as a RESET# pin depending on the status register setting, which need QE=0 and HOLD/RST=1. On the SOP16 package, a dedicated RESET# pin is provided and it is independent of QE bit setting.

The RESET# pin goes low for a period of tRLRH or longer will reset the flash. After reset cycle, the flash is at the following states:

- -Standby mode
- -All the volatile bits will return to the default status as power on.

Figure 2. RESET Condition



GD25Q127C

5. DATA PROTECTION

The GD25Q127Cprovide the following data protection methods:

- Write Enable (WREN) command: The WREN command is set the Write Enable Latch bit (WEL). The WEL bit will return to reset by the following situation:
 - -Power-Up
 - -Write Disable (WRDI)
 - -Write Status Register (WRSR)
 - -Page Program (PP)
 - -Sector Erase (SE) / Block Erase (BE) / Chip Erase (CE)
- ♦ Software Protection Mode:
 - -The Block Protect (BP4, BP3, BP2, BP1, and BP0) bits define the section of the memory array that can be read but not change.
- ♦ Hardware Protection Mode: WP# goes low to protect the writable bit of Status Register.
- Deep Power-Down Mode: In Deep Power-Down Mode, all commands are ignored except the Release from Deep Power-Down Mode command and reset command (66H+99H).

Table 5.1. GD25Q127C Protected area size (CMP=0)

Status Register Content					Memory Content				
BP4	ВР3	BP2	BP1	BP0	Blocks	Blocks Addresses Density		Portion	
Х	Х	0	0	0	NONE	NONE	NONE	NONE	
0	0	0	0	1	252 to 255	FC0000H-FFFFFFH	256KB	Upper 1/64	
0	0	0	1	0	248 to 255	F80000H-FFFFFFH	512KB	Upper 1/32	
0	0	0	1	1	240 to 255	F00000H-FFFFFFH	1MB	Upper 1/16	
0	0	1	0	0	224 to 255	E00000H-FFFFFH	2MB	Upper 1/8	
0	0	1	0	1	192 to 255	C00000H-FFFFFFH	4MB	Upper 1/4	
0	0	1	1	0	128 to 255	800000H-FFFFFFH	8MB	Upper 1/2	
0	1	0	0	1	0 to 3	000000H-03FFFFH	256KB	Lower 1/64	
0	1	0	1	0	0 to 7	000000H-07FFFFH	512KB	Lower 1/32	
0	1	0	1	1	0 to 15	000000H-0FFFFH	1MB	Lower 1/16	
0	1	1	0	0	0 to 31	000000H-1FFFFFH	2MB	Lower 1/8	
0	1	1	0	1	0 to 63	000000H-3FFFFFH	4MB	Lower 1/4	
0	1	1	1	0	0 to 127	000000H-7FFFFFH	8MB	Lower 1/2	
Х	Х	1	1	1	0 to 255	000000H-FFFFFFH	16MB	ALL	
1	0	0	0	1	255	FFF000H-FFFFFFH	4KB	Top Block	
1	0	0	1	0	255	FFE000H-FFFFFFH	8KB	Top Block	
1	0	0	1	1	255	FFC000H-FFFFFFH	16KB	Top Block	
1	0	1	0	Х	255	FF8000H-FFFFFFH	32KB	Top Block	
1	0	1	1	0	255	FF8000H-FFFFFFH	32KB	Top Block	
1	1	0	0	1	0	000000H-000FFFH	4KB	Bottom Block	
1	1	0	1	0	0	000000H-001FFFH	8KB	Bottom Block	
1	1	0	1	1	0	000000H-003FFFH	16KB	Bottom Block	
1	1	1	0	Х	0	000000H-007FFFH	32KB	Bottom Block	



GD25Q127C

1	1	1	1	0	0	000000H-007FFFH	32KB	Bottom Block
---	---	---	---	---	---	-----------------	------	--------------

Table 5.2. GD25Q127C Protected area size (CMP=1)

;	Status F	Register		t	Memory Content				
BP4	BP3	BP2	BP1	BP0	Blocks	Addresses Density		Portion	
Х	Х	0	0	0	0 to 255	000000H-FFFFFFH	ALL	ALL	
0	0	0	0	1	0 to 251	000000H-FBFFFFH	16128KB	Lower 63/64	
0	0	0	1	0	0 to 247	000000H-F7FFFFH	15872KB	Lower 31/32	
0	0	0	1	1	0 to 239	000000H-EFFFFFH	15MB	Lower 15/16	
0	0	1	0	0	0 to 223	000000H-DFFFFFH	14MB	Lower 7/8	
0	0	1	0	1	0 to 191	000000H-BFFFFFH	12MB	Lower 3/4	
0	0	1	1	0	0 to 127	000000H-7FFFFFH	8MB	Lower 1/2	
0	1	0	0	1	4 to 255	040000H-FFFFFFH	16128KB	Upper 63/64	
0	1	0	1	0	8 to 255	080000H-FFFFFFH	15872KB	Upper 31/32	
0	1	0	1	1	16 to 255	100000H-FFFFFFH	15MB	Upper 15/16	
0	1	1	0	0	32 to 255	200000H-FFFFFFH	14MB	Upper 7/8	
0	1	1	0	1	64 to 255	400000H-FFFFFFH	12MB	Upper 3/4	
0	1	1	1	0	128 to 255	800000H-FFFFFFH	8MB	Upper 1/2	
Х	Х	1	1	1	NONE	NONE	NONE	NONE	
1	0	0	0	1	0 to 255	000000H-FFEFFFH	16380KB	L-4095/4096	
1	0	0	1	0	0 to 255	000000H-FFDFFFH	16376KB	L-2047/2048	
1	0	0	1	1	0 to 255	000000H-FFBFFFH	16368KB	L-1023/1024	
1	0	1	0	Х	0 to 255	000000H-FF7FFFH	16352KB	L-511/512	
1	0	1	1	0	0 to 255	000000H-FF7FFFH	16352KB	L-511/512	
1	1	0	0	1	0 to 255	001000H-FFFFFFH	16380KB	U-4095/4096	
1	1	0	1	0	0 to 255	002000H-FFFFFFH	16376KB	U-2047/2048	
1	1	0	1	1	0 to 255	004000H-FFFFFFH	16368KB	U-1023/1024	
1	1	1	0	Х	0 to 255	008000H-FFFFFFH	16352KB	U-511/512	
1	1	1	1	0	0 to 255	008000H-FFFFFFH	16352KB	U-511/512	



GD25Q127C

6. STATUS REGISTER

S23	S22	S21	S20	S19	S18	S17	S16
HOLD/RST	DRV1	DRV0	Reserved	Reserved	LPE	Reserved	Reserved
S15	S14	S13	S12	S11	S10	S9	S8
SUS1	CMP	LB3	LB2	LB1	SUS2	QE	SRP1
S7	S6	S5	S4	S3	S2	S1	S0
SRP0	BP4	BP3	BP2	BP1	BP0	WEL	WIP

The status and control bits of the Status Register are as follows:

WIP bit.

The Write in Progress (WIP) bit indicates whether the memory is busy in program/erase/write status register progress. When WIP bit sets to 1, means the device is busy in program/erase/write status register progress, when WIP bit sets 0, means the device is not in program/erase/write status register progress.

WEL bit.

The Write Enable Latch (WEL) bit indicates the status of the internal Write Enable Latch. When set to 1 the internal Write Enable Latch is set, when set to 0 the internal Write Enable Latch is reset and no Write Status Register, Program or Erase command is accepted.

BP4, BP3, BP2, BP1, BP0 bits.

The Block Protect (BP4, BP3, BP2, BP1 and BP0) bits are non-volatile. They define the size of the area to be software protected against Program and Erase commands. These bits are written with the Write Status Register (WRSR) command. When the Block Protect (BP4, BP3, BP2, BP1, BP0) bits are set to 1, the relevant memory area (as defined in Table1).becomes protected against Page Program (PP), Sector Erase (SE) and Block Erase (BE) commands. The Block Protect (BP4, BP3, BP2, BP1, and BP0) bits can be written provided that the Hardware Protected mode has not been set. The Chip Erase (CE) command is executed, only if the Block Protect (BP2, BP1, and BP0) bits are 0 and CMP=0 or the Block Protect (BP2, BP1, and BP0) bits are 1 and CMP=1.

SRP1, SRP0 bits.

The Status Register Protect (SRP1 and SRP0) bits are non-volatile Read/Write bits in the status register. The SRP bits control the method of write protection: software protection, hardware protection, power supply lock-down or one time programmable protection.

SRP1	SRP0	#WP	Status Register	Description
0	0 0 X		Software Protected	The Status Register can be written to after a Write Enable
	U	^	Software Protected	command, WEL=1.(Default)
0	1	0	Hardware Protected WP#=0, the Status Register locked and cannot be	
0	1	1	Hardware Unprotected	WP#=1, the Status Register is unlocked and can be written
	ı	ı	Hardware Oriprotected	to after a Write Enable command, WEL=1.
1	0	X	Power Supply Lock-	Status Register is protected and cannot be written to again
_ '	O	^	Down ⁽¹⁾⁽²⁾	until the next Power-Down, Power-Up cycle.
1	1 1 X		One Time Program ⁽²⁾	Status Register is permanently protected and cannot be
			One fille i logiality	written to.

NOTE:

1. When SRP1, SRP0= (1, 0), a Power-Down, Power-Up cycle will change SRP1, SRP0 to (0, 0) state.



GD25Q127C

2. This feature is available on special order. (GD25Q127CxxSx)Please contact GigaDevice for details.

QE bit.

The Quad Enable (QE) bit is a non-volatile Read/Write bit in the Status Register that allows Quad operation. When the QE bit is set to 0 (Default) the WP# pin and HOLD# / RESET# pin are enable. When the QE pin is set to 1, the Quad IO2 and IO3 pins are enabled. (It is best to set the QE bit to 0 to avoid short issue if the WP# or HOLD# pin is tied directly to the power supply or ground.)

LB3, LB2, LB1 bits.

The LB3, LB2, LB1 bits are non-volatile One Time Program (OTP) bits in Status Register (S13-S11) that provide the write protect control and status to the Security Registers. The default state of LB3-LB1are 0, the security registers are unlocked. The LB3-LB1 bits can be set to 1 individually using the Write Register instruction. The LB3-LB1 bits are One Time Programmable, once they are set to 1, the Security Registers will become read-only permanently.

CMP bit

The CMP bit is a non-volatile Read/Write bit in the Status Register (S14). It is used in conjunction with the BP4-BP0 bits to provide more flexibility for the array protection. Please see the Status registers Memory Protection table for details. The default setting is CMP=0.

SUS1, SUS2 bits

The SUS1 and SUS2 bits are read only bits in the status register (S15 and S10) that are set to 1 after executing an Program/Erase Suspend (75H) command (The Erase Suspend will set the SUS1 to 1, and the Program Suspend will set the SUS2 to 1). The SUS1 and SUS2 bits are cleared to 0 by Program/Erase Resume (7AH) command, software reset (66H+99H) command as well as a power-down, power-up cycle.

DRV1, DRV0 bits

The DRV1&DRV0 bits are used to determine the output driver strength for the Read operations.

DRV1,DRV0	Driver Strength
00	100%
01	75%
10	50% (default)
11	25%

HOLD/RST bit

The HOLD/RST bit is used to determine whether HOLD# or RESET# function should be implemented on the hardware pin for 8-pin packages. When HOLD/RST=0, the pin acts as HOLD#, When the HOLD/RST=1, the pin acts as RESET#. However, the HOLD# or RESET# function are only available when QE=0, If QE=1, The HOLD# and RESET# functions are disabled, the pin acts as dedicated data I/O pin.

LPE bit

The Low Power Enable (LPE) bit is a non-volatile writable bit, indicating the status of Low Power Mode (LPM). When LPE bit sets to 1, it means the device is in Low Power Mode, when LPE bit sets 0 (default), it means the device is not in Low Power Mode.

GD25Q127C

7. COMMANDS DESCRIPTION

All commands, addresses and data are shifted in and out of the device, beginning with the most significant bit on the first rising edge of SCLK after CS# is driven low. Then, the one-byte command code must be shifted in to the device, with most significant bit first on SI, and each bit being latched on the rising edges of SCLK.

See Table 7.1., every command sequence starts with a one-byte command code. Depending on the command, this might be followed by address bytes, or by data bytes, or by both or none. CS# must be driven high after the last bit of the command sequence has been completed. For the command of Read, Fast Read, Read Status Register or Release from Deep Power-Down, and Read Device ID, the shifted-in command sequence is followed by a data-out sequence. All read instruction can be completed after any bit of the data-out sequence is being shifted out, and then CS# must be driven high to return to deselected status.

For the command of Page Program, Sector Erase, Block Erase, Chip Erase, Write Status Register, Write Enable, Write Disable or Deep Power-Down command, CS# must be driven high exactly at a byte boundary, otherwise the command is rejected, and is not executed. That is CS# must be driven high when the number of clock pulses after CS# being driven low is an exact multiple of eight. For Page Program, if at any time the input byte is not a full byte, nothing will happen and WEL will not be reset.

Table 7.1. Commands (Standard/Dual/Quad SPI)

Command Name	Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6	n-Bytes
Write Enable	06H						
Write Disable	04H						
Volatile SR	50H						
Write Enable							
Read Status Register-1	05H	(S7-S0)					(continuous)
Read Status Register-2	35H	(S15-S8)					(continuous)
Read Status Register-3	15H	(S23-S16)					
Write Status Register-1	01H	S7-S0					
Write Status Register-2	31H	S15-S8					
Write Status Register-3	11H	S23-S16					
Read Data	03H	A23-A16	A15-A8	A7-A0	(D7-D0)	(Next byte)	(continuous)
Fast Read	0BH	A23-A16	A15-A8	A7-A0	dummy	(D7-D0)	(continuous)
Dual Output	3BH	A23-A16	A15-A8	A7-A0	dummy	(D7-D0) ⁽¹⁾	(continuous)
Fast Read							
Dual I/O Fast Read	BBH	A23-A8 ⁽²⁾	A7-A0 M7-M0 ⁽²⁾	(D7-D0) ⁽¹⁾			(continuous)
Quad Output	6BH	A23-A16	A15-A8	A7-A0	dummy	(D7-D0) ⁽³⁾	(continuous)
Fast Read							
Quad I/O	EBH	A23-A0	dummy ⁽⁵⁾	(D7-D0) ⁽³⁾			(continuous)
Fast Read		M7-M0 ⁽⁴⁾					
Quad I/O Word	E7H	A23-A0	dummy ⁽⁶⁾	(D7-D0) ⁽³⁾			(continuous)
Fast Read ⁽⁷⁾		M7-M0 ⁽⁴⁾					
Page Program	02H	A23-A16	A15-A8	A7-A0	D7-D0	Next byte	
Quad Page Program	32H	A23-A16	A15-A8	A7-A0	D7-D0		
Sector Erase	20H	A23-A16	A15-A8	A7-A0			
Block Erase(32K)	52H	A23-A16	A15-A8	A7-A0			
Block Erase(64K)	D8H	A23-A16	A15-A8	A7-A0			
Chip Erase	C7/60						
	Н						
Enable Reset	66H						
Reset	99H						
Set Burst with Wrap	77H	dummy ⁽⁹⁾					



GD25Q127C

		W7-W0					
Program/Erase Suspend	75H						
Program/Erase Resume	7AH						
Release From Deep Power-Down, And Read Device ID	ABH	dummy	dummy	dummy	(DID7- DID0)		(continuous)
Release From Deep Power-Down	ABH						
Deep Power-Down	В9Н					1	
Manufacturer/ Device ID	90H	dummy	dummy	00H	(MID7- MID0)	(DID7- DID0)	(continuous)
Manufacturer/ Device ID by Dual I/O	92H	A23-A8	A7-A0, M7-M0	(MID7- MID0) (DID7- DID0)			(continuous)
Manufacturer/ Device ID by Quad I/O	94H	A23-A0, M7-M0	dummy (10)(MID7- MID0) (DID7- DID0)				(continuous)
Read Identification	9FH	(MID7- MID0)	(JDID15- JDID8)	(JDID7- JDID0)			(continuous)
Read Serial Flash Discoverable Parameter	5AH	A23-A16	A15-A8	A7-A0	dummy	(D7-D0)	(continuous)
Read Unique ID	4BH	dummy	dummy	dummy	dummy	(UID7- UID0)	(continuous)
Erase Security Registers ⁽⁸⁾	44H	A23-A16	A15-A8	A7-A0			
Program Security Registers ⁽⁸⁾	42H	A23-A16	A15-A8	A7-A0	D7-D0	D7-D0	
Read Security Registers ⁽⁸⁾	48H	A23-A16	A15-A8	A7-A0	dummy	(D7-D0)	

NOTE:

1. Dual Output data

IO0=(D6,D4,D2,D0)

IO1=(D7,D5,D3,D1)

2. Dual Input Address

IO0=A22,A20,A18,A16,A14,A12,A10,A8 A6,A4,A2,A0,M6,M4,M2,M0

IO1=A23,A21,A19,A17,A15,A13,A11,A9 A7,A5,A3,A1,M7,M5,M3,M1

3. Quad Output Data

IO0=(D4,D0,....)

IO1=(D5,D1,....)

IO2=(D6,D2,....)

IO3=(D7,D3,....)

4. Quad Input Address

IO0=A20,A16,A12,A8, A4,A0,M4,M0

IO1=A21,A17,A13,A9, A5,A1,M5,M1

IO2=A22,A18,A14,A10,A6,A2,M6,M2

IO3=A23,A19,A15,A11,A7,A3,M7,M3

5. Fast Read Quad I/O Data

С



3.3V Uniform Sector Dual and Quad Serial Flash

GD25Q127C

IO0=(x,x,x,x, D4, D0,...)

IO1=(x,x,x,x, D5, D1,...)

IO2=(x,x,x,x, D6, D2,...)

IO3=(x,x,x,x, D7, D3,...)

6. Fast Word Read Quad I/O Data

IO0=(x,x, D4, D0,...)

IO1=(x,x, D5, D1,...)

IO2=(x,x, D6, D2,...)

IO3=(x,x, D7, D3,...)

- 7. Fast Word Read Quad I/O Data: the lowest address bit must be 0.
- 8. Security Registers Address:

Security Register1: A23-A16=00H, A15-A10=000100b, A9-A0=Byte Address;

Security Register2: A23-A16=00H, A15-A10=001000b, A9-A0=Byte Address;

Security Register3: A23-A16=00H, A15-A10=001100b, A9-A0=Byte Address.

9. Dummy bits and Wrap Bits

IO0=(x,x, x,x, x,x, W4,x)

IO1=(x,x, x,x, x,x, W5,x)

IO2=(x,x, x,x, x,x, W6, x)

103=(x,x, x,x, x,x, x, x)

10. Address, Continuous Read Mode bits, Dummy bits, Manufacture ID and Device ID

IO0=(A20, A16, A12, A8, A4, A0, M4, M0, x,x, x,x, MID4, MID0, DID4, DID0, ...)

IO1=(A21, A17, A13, A9, A5, A1, M5, M1, x,x, x,x, MID5, MID1, DID5, DID1, ...)

IO2=(A22, A18, A14, A10, A6, A2, M6, M2,x,x, x,x, MID6, MID2, DID6, DID2, ...)

IO3=(A23, A19, A15, A11, A7, A3, M7, M3, x,x, x,x, MID7, MID3, DID7, DID3, ...)

Table 7.2. Table of ID Definitions for GD25Q127C

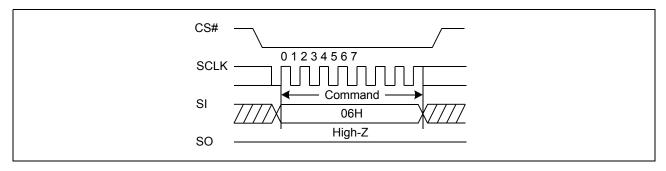
Operation Code	MID7-MID0	ID15-ID8	ID7-ID0
9FH	C8	40	18
90H/92H/94H	C8		17
ABH			17

GD25Q127C

7.1. Write Enable (WREN) (06H)

The Write Enable (WREN) command is for setting the Write Enable Latch (WEL) bit. The Write Enable Latch (WEL) bit must be set prior to every Page Program (PP), Sector Erase (SE), Block Erase (BE), Chip Erase (CE), Write Status Register (WRSR) and Erase/Program Security Registers command. The Write Enable (WREN) command sequence: CS# goes low → sending the Write Enable command → CS# goes high.

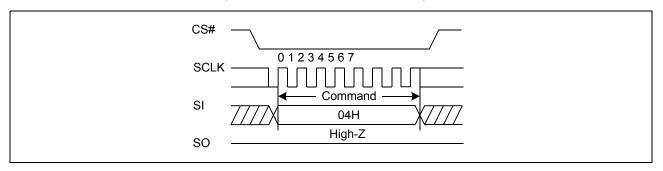
Figure 3. Write Enable Sequence Diagram



7.2. Write Disable (WRDI) (04H)

The Write Disable command is for resetting the Write Enable Latch (WEL) bit. The Write Disable command sequence: CS# goes low→Sending the Write Disable command →CS# goes high. The WEL bit is reset by following condition: Power-up and upon completion of the Write Status Register, Page Program, Sector Erase, Block Erase, Chip Erase, Erase/Program Security Registers and Reset commands.

Figure 4. Write Disable Sequence Diagram



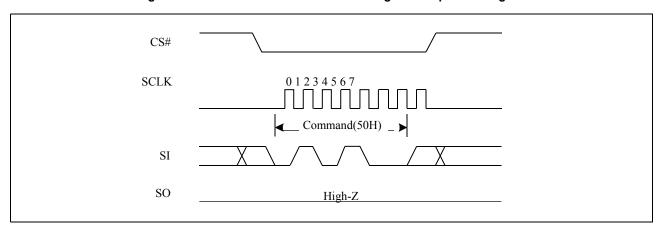
7.3. Write Enable for Volatile Status Register (50H)

The non-volatile Status Register bits can also be written to as volatile bits. This gives more flexibility to change the system configuration and memory protection schemes quickly without waiting for the typical non-volatile bit write cycles or affecting the endurance of the Status Register non-volatile bits. The Write Enable for Volatile Status Register command must be issued prior to a Write Status Register command, and any other commands cannot be inserted between them. Otherwise, Write Enable for Volatile Status Register will be cleared. The Write Enable for Volatile Status Register command will not set the Write Enable Latch bit, it is only valid for the Write Status Register command to change the volatile Status Register bit values.



GD25Q127C

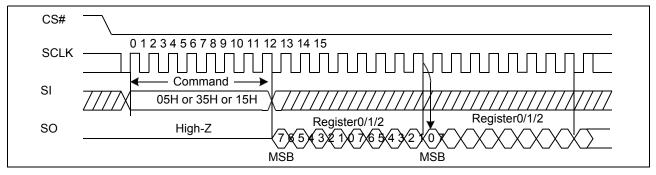
Figure 5. Write Enable for Volatile Status Register Sequence Diagram



7.4. Read Status Register (RDSR) (05H or 35H or 15H)

The Read Status Register (RDSR) command is for reading the Status Register. The Status Register may be read at any time, even while a Program, Erase or Write Status Register cycle is in progress. When one of these cycles is in progress, it is recommended to check the Write in Progress (WIP) bit before sending a new command to the device. It is also possible to read the Status Register continuously. For command code "05H"/ "35H" / "15H", the SO will output Status Register bits S7~S0/ S15-S8 / S23-S16.

Figure 6. Read Status Register Sequence Diagram



7.5. Write Status Register (WRSR) (01H or 31H or 11H)

The Write Status Register (WRSR) command allows new values to be written to the Status Register. Before it can be accepted, a Write Enable (WREN) command must previously have been executed. After the Write Enable (WREN) command has been decoded and executed, the device sets the Write Enable Latch (WEL).

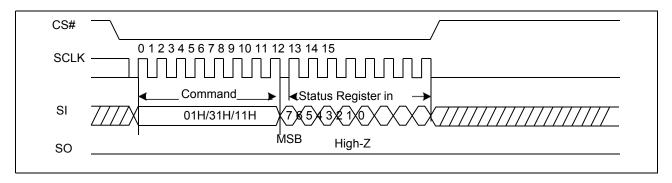
The Write Status Register (WRSR) command has no effect on S20, S19, S17, S16, S15, S10, S1 and S0 of the Status Register. CS# must be driven high after the eighth of the data byte has been latched in. If not, the Write Status Register (WRSR) command is not executed. As soon as CS# is driven high, the self-timed Write Status Register cycle (whose duration is tw) is initiated. While the Write Status Register cycle is in progress, the Status Register may still be read to check the value of the Write In Progress (WIP) bit. The Write In Progress (WIP) bit is 1 during the self-timed Write Status Register cycle, and is 0 when it is completed. When the cycle is completed, the Write Enable Latch (WEL) is reset.

The Write Status Register (WRSR) command allows the user to change the values of the Block Protect (BP4, BP3, BP2, BP1, and BP0) bits, to define the size of the area that is to be treated as read-only. The Write Status Register (WRSR) command also allows the user to set or reset the Status Register Protect (SRP1 and SRP0) bits in accordance with the Write Protect (WP#) signal. The Status Register Protect (SRP1 and SRP0) bits and Write Protect (WP#) signal allow the device to be put in the Hardware Protected Mode. The Write Status Register (WRSR) command is not executed once the

GD25Q127C

Hardware Protected Mode is entered.

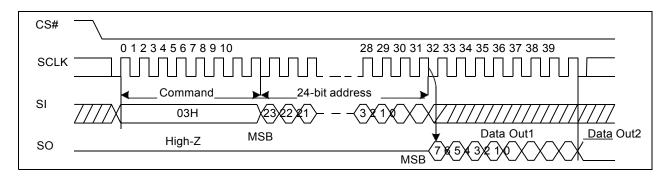
Figure 7. Write Status Register Sequence Diagram



7.6. Read Data Bytes (READ) (03H)

The Read Data Bytes (READ) command is followed by a 3-byte address (A23-A0), and each bit is latched-in on the rising edge of SCLK. Then the memory content, at that address, is shifted out on SO, each bit being shifted out, at a Max frequency f_R , during the falling edge of SCLK. Then the memory content at that address is shifted out on SO. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out. The whole memory can, therefore, be read with a single Read Data Bytes (READ) command. Any Read Data Bytes (READ) command, while an Erase, Program or Write cycle is in progress, is rejected without having any effects on the cycle that is in progress.

Figure8. Read Data Bytes Sequence Diagram



GD25Q127C

Read Data Bytes at Higher Speed (Fast Read) (0BH) 7.7.

The Read Data Bytes at Higher Speed (Fast Read) command is for quickly reading data out. It is followed by a 3-byte address (A23-A0) and a dummy byte, each bit being latched-in during the rising edge of SCLK. Then the memory content, at that address, is shifted out on SO, each bit being shifted out, at a Max frequency fc, during the falling edge of SCLK. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out.

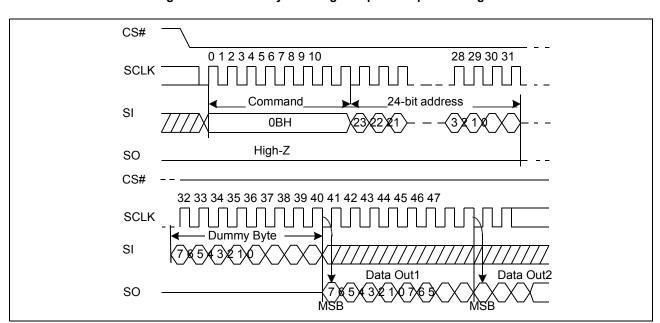
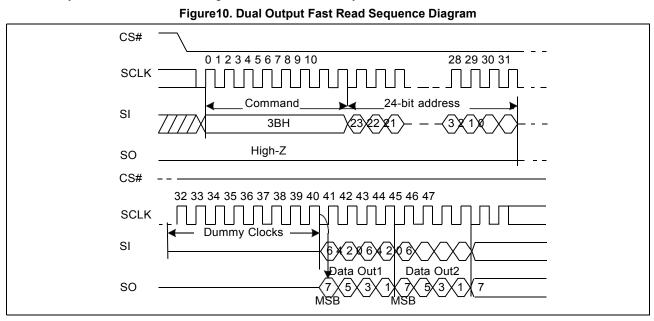


Figure 9. Read Data Bytes at Higher Speed Sequence Diagram

7.8. Dual Output Fast Read (3BH)

The Dual Output Fast Read command is followed by 3-byte address (A23-A0) and a dummy byte, each bit being latched in during the rising edge of SCLK, then the memory contents are shifted out 2-bit per clock cycle from SI and SO. The command sequence is shown in followed Figure 10. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out.



GD25Q127C

7.9. Quad Output Fast Read (6BH)

The Quad Output Fast Read command is followed by 3-byte address (A23-A0) and a dummy byte, each bit being latched in during the rising edge of SCLK, then the memory contents are shifted out 4-bit per clock cycle from IO3, IO2, IO1 and IO0. The command sequence is shown in followed Figure 11. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out.

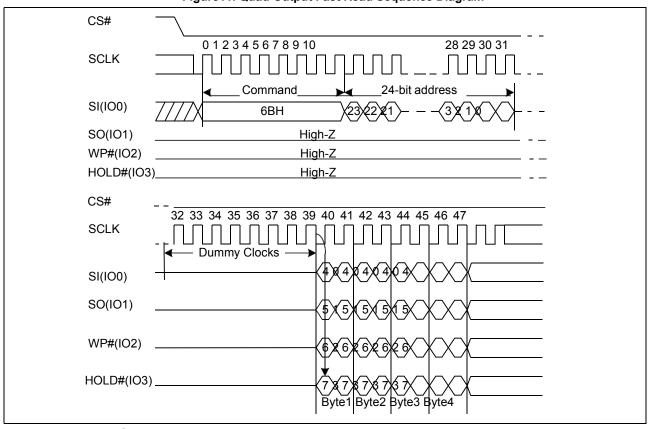


Figure 11. Quad Output Fast Read Sequence Diagram

7.10. **Dual I/O Fast Read (BBH)**

The Dual I/O Fast Read command is similar to the Dual Output Fast Read command but with the capability to input the 3-byte address (A23-0) and a "Continuous Read Mode" byte 2-bit per clock by SI and SO, each bit being latched in during the rising edge of SCLK, then the memory contents are shifted out 2-bit per clock cycle from SI and SO. The command sequence is shown in followed Figure 12. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out.

Dual I/O Fast Read with "Continuous Read Mode"

The Dual I/O Fast Read command can further reduce command overhead through setting the "Continuous Read Mode" bits (M7-4) after the input 3-byte address (A23-A0). If the "Continuous Read Mode" bits (M5-4)= (1, 0), then the next Dual I/O Fast Read command (after CS# is raised and then lowered) does not require the BBH command code. The command sequence is shown in followed Figure 12a. If the "Continuous Read Mode" bits (M5-4) do not equal (1, 0), the next command requires the first BBH command code, thus returning to normal operation. A "Continuous Read Mode" Reset command can be used to reset (M5-4) before issuing normal command.



GD25Q127C

Figure 12. Dual I/O Fast Read Sequence Diagram (M5-4≠(1, 0))

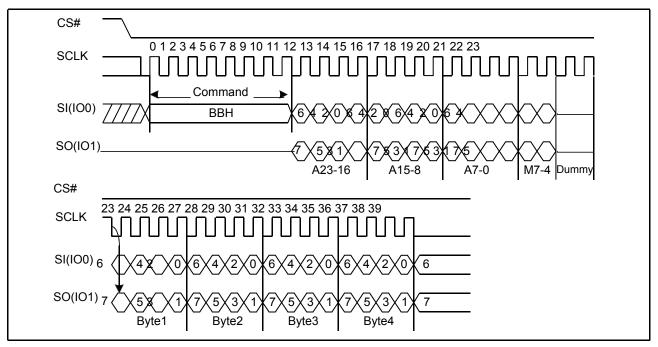
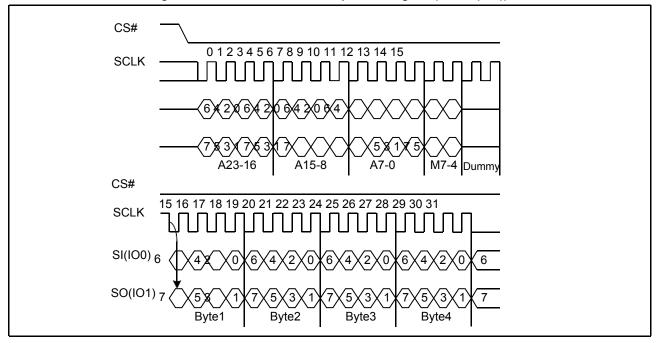


Figure 12a. Dual I/O Fast Read Sequence Diagram (M5-4= (1, 0))



7.11. Quad I/O Fast Read (EBH)

The Quad I/O Fast Read command is similar to the Dual I/O Fast Read command but with the capability to input the 3-byte address (A23-0) and a "Continuous Read Mode" byte and 4-dummy clock4-bit per clock by IO0, IO1, IO2, IO3, each bit being latched in during the rising edge of SCLK, then the memory contents are shifted out 4-bit per clock cycle from IO0, IO1, IO2, IO3. The command sequence is shown in followed Figure 13. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out. The Quad Enable bit (QE) of Status Register (S9) must be set to enable for the Quad I/O Fast read command.

GD25Q127C

Quad I/O Fast Read with "Continuous Read Mode"

The Quad I/O Fast Read command can further reduce command overhead through setting the "Continuous Read Mode" bits (M7-0) after the input 3-byte address (A23-A0). If the "Continuous Read Mode" bits (M5-4) = (1, 0), then the next Quad I/O Fast Read command (after CS# is raised and then lowered) does not require the EBH command code. The command sequence is shown in followed Figure 13a. If the "Continuous Read Mode" bits (M5-4) do not equal to (1, 0), the next command requires the first EBH command code, thus returning to normal operation. A "Continuous Read Mode" Reset command can be used to reset (M5-4) before issuing normal command.

Figure 13. Quad I/O Fast Read Sequence Diagram (M5-4≠(1, 0))

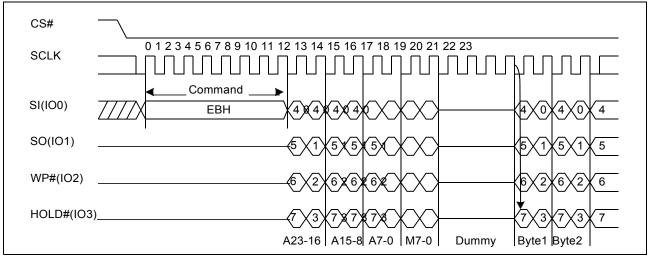
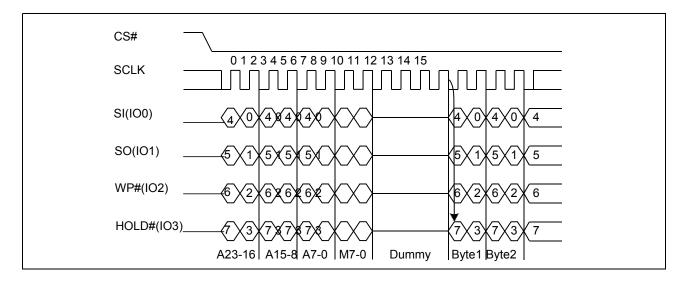


Figure 13a. Quad I/O Fast Read Sequence Diagram (M5-4= (1, 0))



Quad I/O Fast Read with "8/16/32/64-Byte Wrap Around" in Standard SPI Mode

The Quad I/O Fast Read command can be used to access a specific portion within a page by issuing "Set Burst with Wrap" (77H) commands prior to EBH. The "Set Burst with Wrap" (77H) command can either enable or disable the "Wrap Around" feature for the following EBH commands. When "Wrap Around" is enabled, the data being accessed can be limited to either an8/16/32/64-byte section of a 256-byte page. The output data starts at the initial address specified in the command, once it reaches the ending boundary of the 8/16/32/64-byte section, the output will wrap around the beginning boundary automatically until CS# is pulled high to terminate the command.

The Burst with Wrap feature allows applications that use cache to quickly fetch a critical address and then fill the cache



GD25Q127C

afterwards within a fixed length (8/16/32/64-byte) of data without issuing multiple read commands. The "Set Burst with Wrap" command allows three "Wrap Bits" W6-W4 to be set. The W4 bit is used to enable or disable the "Wrap Around" operation while W6-W5 is used to specify the length of the wrap around section within a page.

7.12. Quad I/O Word Fast Read (E7H)

The Quad I/O Word Fast Read command is similar to the Quad I/O Fast Read command except that the lowest address bit (A0) must equal 0 and only 2-dummy clock. The command sequence is shown in followed Figure 14. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out. The Quad Enable bit (QE) of Status Register (S9) must be set to enable for the Quad I/O Word Fast read command.

Quad I/O Word Fast Read with "Continuous Read Mode"

The Quad I/O Word Fast Read command can further reduce command overhead through setting the "Continuous Read Mode" bits (M7-0) after the input 3-byte address (A23-A0). If the "Continuous Read Mode" bits (M5-4) =(1, 0), then the next Quad I/O Word Fast Read command (after CS# is raised and then lowered) does not require the E7H command code. The command sequence is shown in followed Figure14a. If the "Continuous Read Mode" bits (M5-4) do not equal to (1, 0), the next command requires the first E7H command code, thus returning to normal operation. A "Continuous Read Mode" Reset command can be used to reset (M5-4) before issuing normal command.

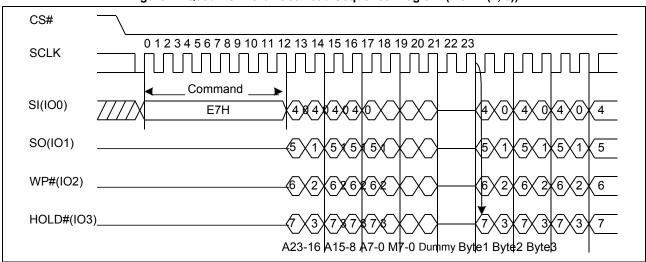
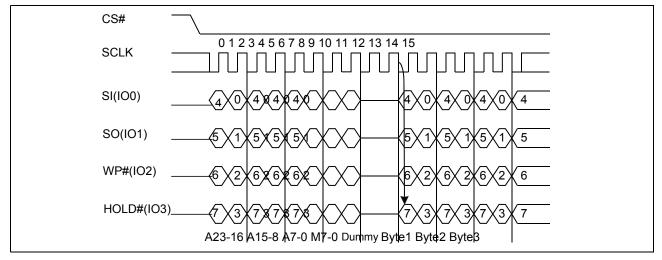


Figure 14. Quad I/O Word Fast Read Sequence Diagram (M5-4≠ (1, 0))

Figure 14a. Quad I/O Word Fast Read Sequence Diagram (M5-4= (1, 0))





GD25Q127C

Quad I/O Word Fast Read with "8/16/32/64-Byte Wrap Around" in Standard SPI Mode

The Quad I/O Word Fast Read command can be used to access a specific portion within a page by issuing "Set Burst with Wrap" (77H) commands prior to E7H. The "Set Burst with Wrap" (77H) command can either enable or disable the "Wrap Around" feature for the following E7H commands. When "Wrap Around" is enabled, the data being accessed can be limited to either an 8/16/32/64-byte section of a 256-byte page. The output data starts at the initial address specified in the command, once it reaches the ending boundary of the 8/16/32/64-byte section, the output will wrap around the beginning boundary automatically until CS# is pulled high to terminate the command.

The Burst with Wrap feature allows applications that use cache to quickly fetch a critical address and then fill the cache afterwards within a fixed length (8/16/32/64-byte) of data without issuing multiple read commands. The "Set Burst with Wrap" command allows three "Wrap Bits" W6-W4 to be set. The W4 bit is used to enable or disable the "Wrap Around" operation while W6-W5 is used to specify the length of the wrap around section within a page.

7.13. Set Burst with Wrap (77H)

The Set Burst with Wrap command is used in conjunction with "Quad I/O Fast Read" and "Quad I/O Word Fast Read" command to access a fixed length of 8/16/32/64-byte section within a 256-byte page.

The Set Burst with Wrap command sequence: CS# goes low \rightarrow Send Set Burst with Wrap command \rightarrow Send 24 dummy bits \rightarrow Send 8 bits "Wrap bits" \rightarrow CS# goes high.

	<u> </u>	<u> </u>			
W6,W5	W	4=0	W4=1 (default)		
	Wrap Around	Wrap Length	Wrap Around	Wrap Length	
0, 0	Yes	8-byte	No	N/A	
0, 1	Yes	16-byte	No	N/A	
1, 0	Yes	32-byte	No	N/A	
1, 1	Yes	64-byte	No	N/A	

If the W6-W4 bits are set by the Set Burst with Wrap command, all the following "Quad I/O Fast Read" and "Quad I/O Word Fast Read" command will use the W6-W4 setting to access the 8/16/32/64-byte section within any page. To exit the "Wrap Around" function and return to normal read operation, another Set Burst with Wrap command should be issued to set W4=1.

CS#

SCLK

0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15

SI(IO0)

77H

XXXXX4

SO(IO1)

WP#(IO2)

HOLD#(IO3)

XXXXX

W6-W4

Figure 15. Set Burst with Wrap Sequence Diagram

GD25Q127C

7.14. Page Program (PP) (02H)

The Page Program (PP) command is for programming the memory. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit before sending the Page Program command.

The Page Program (PP) command is entered by driving CS# Low, followed by the command code, three address bytes and at least one data byte on SI. If the 8 least significant address bits (A7-A0) are not all zero, all transmitted data that goes beyond the end of the current page are programmed from the start address of the same page (from the address whose 8 least significant bits (A7-A0) are all zero). CS# must be driven low for the entire duration of the sequence. The Page Program command sequence: CS# goes low → sending Page Program command → 3-byte address on SI → at least 1 byte data on SI →CS# goes high. The command sequence is shown in Figure16. If more than 256 bytes are sent to the device, previously latched data are discarded and the last 256 data bytes are guaranteed to be programmed correctly within the same page. If less than 256 data bytes are sent to device, they are correctly programmed at the requested addresses without having any effects on the other bytes of the same page. CS# must be driven high after the eighth bit of the last data byte has been latched in; otherwise the Page Program (PP) command is not executed.

As soon as CS# is driven high, the self-timed Page Program cycle (whose duration is t_{PP}) is initiated. While the Page Program cycle is in progress, the Status Register may be read to check the value of the Write in Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Page Program cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset.

A Page Program (PP) command applied to a page which is protected by the Block Protect (BP4, BP3, BP2, BP1, and BP0) is not executed.

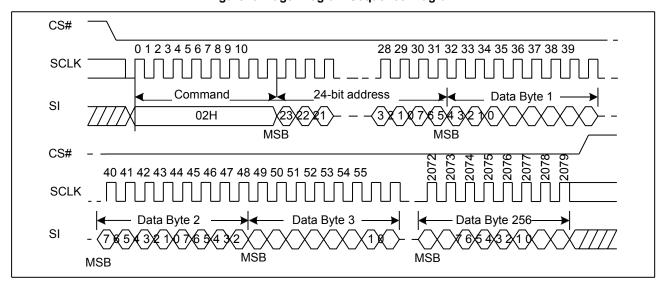


Figure 16. Page Program Sequence Diagram

7.15. Quad Page Program (32H)

The Quad Page Program command is for programming the memory using four pins: IO0, IO1, IO2, and IO3. To use Quad Page Program the Quad enable in status register Bit9 must be set (QE=1).A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit before sending the Page Program command. The quad Page Program command is entered by driving CS# Low, followed by the command code (32H), three address bytes and at least one data byte on IO pins.

The command sequence is shown in Figure 17. If more than 256 bytes are sent to the device, previously latched data are discarded and the last 256 data bytes are guaranteed to be programmed correctly within the same page. If less than 256 data bytes are sent to device, they are correctly programmed at the requested addresses without having any effects on



GD25Q127C

the other bytes of the same page. CS# must be driven high after the eighth bit of the last data byte has been latched in; otherwise the Quad Page Program (PP) command is not executed.

As soon as CS# is driven high, the self-timed Quad Page Program cycle (whose duration is tpp) is initiated. While the Quad Page Program cycle is in progress, the Status Register may be read to check the value of the Write In Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Quad Page Program cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset.

A Quad Page Program command applied to a page which is protected by the Block Protect (BP4, BP3, BP2, BP1, and BP0) is not executed.

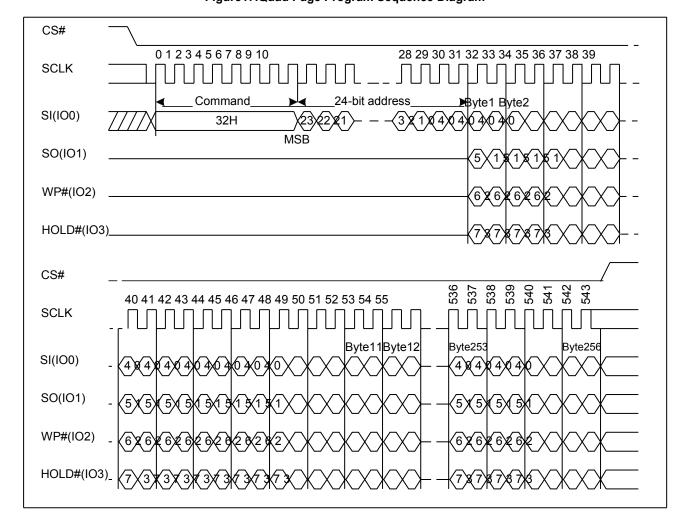


Figure 17. Quad Page Program Sequence Diagram

7.16. Sector Erase (SE) (20H)

The Sector Erase (SE) command is erased the all data of the chosen sector. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit. The Sector Erase (SE) command is entered by driving CS# low, followed by the command code, and 3-address byte on SI. Any address inside the sector is a valid address for the Sector Erase (SE) command. CS# must be driven low for the entire duration of the sequence.

The Sector Erase command sequence: CS# goes low \rightarrow sending Sector Erase command \rightarrow 3-byte address on SI \rightarrow CS# goes high. The command sequence is shown in Figure 18. CS# must be driven high after the eighth bit of the last address byte has been latched in; otherwise the Sector Erase (SE) command is not executed. As soon as CS# is driven high, the self-timed Sector Erase cycle (whose duration is t_{SE}) is initiated. While the Sector Erase cycle is in progress, the



GD25Q127C

Status Register may be read to check the value of the Write in Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Sector Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. A Sector Erase (SE) command applied to a sector which is protected by the Block Protect (BP4, BP3, BP2, BP1, and BP0) bit is not executed.

CS#

SCLK 0123456789 293031

SCLK Command 24 Bits Address 24 Bits Address 20H 23322 - - - 2 × 0 × ////

Figure 18. Sector Erase Sequence Diagram

7.17. 32KB Block Erase (BE) (52H)

The 32KB Block Erase (BE) command is erased the all data of the chosen block. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit. The 32KB Block Erase (BE) command is entered by driving CS# low, followed by the command code, and three address bytes on SI. Any address inside the block is a valid address for the 32KB Block Erase (BE) command. CS# must be driven low for the entire duration of the sequence.

The 32KB Block Erase command sequence: CS# goes low \rightarrow sending 32KB Block Erase command \rightarrow 3-byte address on SI \rightarrow CS# goes high. The command sequence is shown in Figure19. CS# must be driven high after the eighth bit of the last address byte has been latched in; otherwise the 32KB Block Erase (BE) command is not executed. As soon as CS# is driven high, the self-timed Block Erase cycle (whose duration is t_{BE}) is initiated. While the Block Erase cycle is in progress, the Status Register may be read to check the value of the Write in Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Block Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. A 32KB Block Erase (BE) command applied to a block which is protected by the Block Protect (BP4, BP3, BP2, BP1, and BP0) bits is not executed.

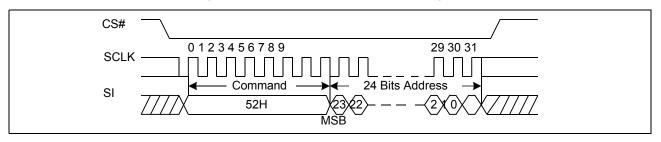


Figure 19. 32KB Block Erase Sequence Diagram

7.18. 64KB Block Erase (BE) (D8H)

The 64KB Block Erase (BE) command is erased the all data of the chosen block. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit. The 64KB Block Erase (BE) command is entered by driving CS# low, followed by the command code, and three address bytes on SI. Any address inside the block is a valid address for the 64KB Block Erase (BE) command. CS# must be driven low for the entire duration of the sequence.

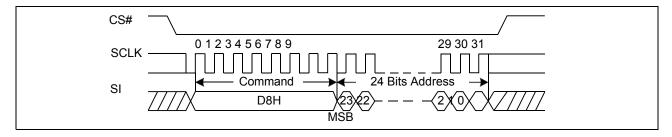
The 64KB Block Erase command sequence: CS# goes low \rightarrow sending 64KB Block Erase command \rightarrow 3-byte address on SI \rightarrow CS# goes high. The command sequence is shown in Figure20. CS# must be driven high after the eighth bit of the last address byte has been latched in; otherwise the 64KB Block Erase (BE) command is not executed. As soon as CS# is



GD25Q127C

driven high, the self-timed Block Erase cycle (whose duration is t_{BE}) is initiated. While the Block Erase cycle is in progress, the Status Register may be read to check the value of the Write in Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Block Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. A 64KB Block Erase (BE) command applied to a block which is protected by the Block Protect (BP4, BP3, BP2, BP1, and BP0) bits is not executed.

Figure 20. 64KB Block Erase Sequence Diagram



7.19. Chip Erase (CE) (60/C7H)

The Chip Erase (CE) command is erased the all data of the chip. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit .The Chip Erase (CE) command is entered by driving CS# Low, followed by the command code on Serial Data Input (SI). CS# must be driven Low for the entire duration of the sequence.

The Chip Erase command sequence: CS# goes low \rightarrow sending Chip Erase command \rightarrow CS# goes high. The command sequence is shown in Figure21. CS# must be driven high after the eighth bit of the command code has been latched in; otherwise the Chip Erase command is not executed. As soon as CS# is driven high, the self-timed Chip Erase cycle (whose duration is t_{CE}) is initiated. While the Chip Erase cycle is in progress, the Status Register may be read to check the value of the Write in Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Chip Erase cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. The Chip Erase (CE) command is executed if the Block Protect (BP2, BP1, and BP0) bits are 1 and CMP=1. The Chip Erase (CE) command is ignored if one or more sectors are protected

SCLK 01234567
SCLK Command Command 60H or C7H

Figure 21. Chip Erase Sequence Diagram

7.20. Deep Power-Down (DP) (B9H)

Executing the Deep Power-Down (DP) command is the only way to put the device in the lowest consumption mode (the Deep Power-Down Mode). It can also be used as an extra software protection mechanism, while the device is not in active use, since in this mode, the device ignores all Write, Program and Erase commands. Driving CS# high deselects the device, and puts the device in the Standby Mode (if there is no internal cycle currently in progress). But this mode is not the Deep Power-Down Mode. The Deep Power-Down Mode can only be entered by executing the Deep Power-Down (DP) command. Once the device has entered the Deep Power-Down Mode, all commands are ignored except the Release from Deep Power-Down and Read Device ID (RDI) (ABH) or Enable Reset (66H) and Reset (99H) commands. These commands can release the device from this mode. The Release from Deep Power-Down and Read Device ID (RDI) command releases



GD25Q127C

the device from deep power down mode, also allows the Device ID of the device to be output on SO.

The Deep Power-Down Mode automatically stops at Power-Down, and the device is in the Standby Mode after Power-Up. The Deep Power-Down (DP) command is entered by driving CS# low, followed by the command code on SI. CS# must be driven low for the entire duration of the sequence.

The Deep Power-Down command sequence: CS# goes low \rightarrow sending Deep Power-Down command \rightarrow CS# goes high. The command sequence is shown in Figure 22. CS# must be driven high after the eighth bit of the command code has been latched in; otherwise the Deep Power-Down (DP) command is not executed. As soon as CS# is driven high, it requires a delay of t_{DP} before the supply current is reduced to t_{CC2} and the Deep Power-Down Mode is entered. Any Deep Power-Down (DP) command, while an Erase, Program or Write cycle is in progress, is rejected without having any effects on the cycle that is in progress.

SCLK

O 1 2 3 4 5 6 7

SCLK

Command
Stand-by mode Deep Power-down mode

B9H

Figure 22. Deep Power-Down Sequence Diagram

7.21. Release from Deep Power-Down and Read Device ID (RDI) (ABH)

The Release from Power-Down and Read Device ID command is a multi-purpose command. It can be used to release the device from the Power-Down state or obtain the devices electronic identification (ID) number.

To release the device from the Power-Down state, the command is issued by driving the CS# pin low, shifting the instruction code "ABH" and driving CS# high as shown below. Release from Power-Down will take the time duration of trees (See AC Characteristics) before the device will resume normal operation and other command are accepted. The CS# pin must remain high during the trees time duration.

When used only to obtain the Device ID while not in the Power-Down state, the command is initiated by driving the CS# pin low and shifting the instruction code "ABH" followed by 3-dummy byte. The Device ID bits are then shifted out on the falling edge of SCLK with most significant bit (MSB) first as shown below. The Device ID value is listed in Manufacturer and Device Identification table. The Device ID can be read continuously. The command is completed by driving CS# high.

When used to release the device from the Power-Down state and obtain the Device ID, the command is the same as previously described, except that after CS# is driven high it must remain high for a time duration of t_{RES2} (See AC Characteristics). After this time duration the device will resume normal operation and other command will be accepted. If the Release from Power-Down / Device ID command is issued while an Erase, Program or Write cycle is in process (when WIP equal 1) the command is ignored and will not have any effects on the current cycle.

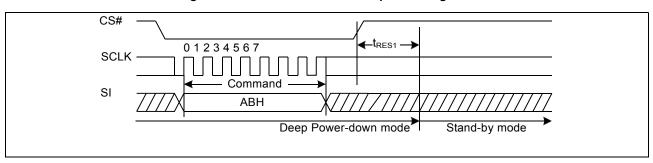
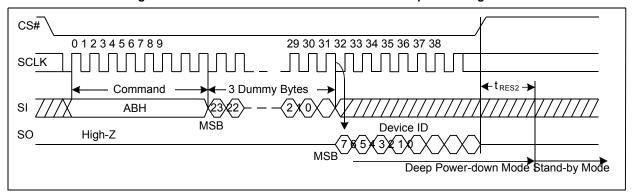


Figure 23. Release Power-Down Sequence Diagram



GD25Q127C

Figure 24. Release Power-Down/Read Device ID Sequence Diagram



7.22. Read Manufacture ID/ Device ID (REMS) (90H)

The Read Manufacturer/Device ID command is an alternative to the Release from Power-Down / Device ID command that provides both the JEDEC assigned Manufacturer ID and the specific Device ID.

The command is initiated by driving the CS# pin low and shifting the command code "90H" followed by a 24-bit address (A23-A0) of 000000H. After which, the Manufacturer ID and the Device ID are shifted out on the falling edge of SCLK with most significant bit (MSB) first as shown in Figure 25. If the 24-bit address is initially set to 000001H, the Device ID will be read first.

CS# 28 29 30 31 012345678910 **SCLK** -bit address Command SI 90H High-Z SO CS# 37 38 39 40 41 42 43 44 45 46 47 **SCLK** SI Device ID SO

Figure 25. Read Manufacture ID/ Device ID Sequence Diagram

7.23. Read Manufacture ID/ Device ID Dual I/O (92H)

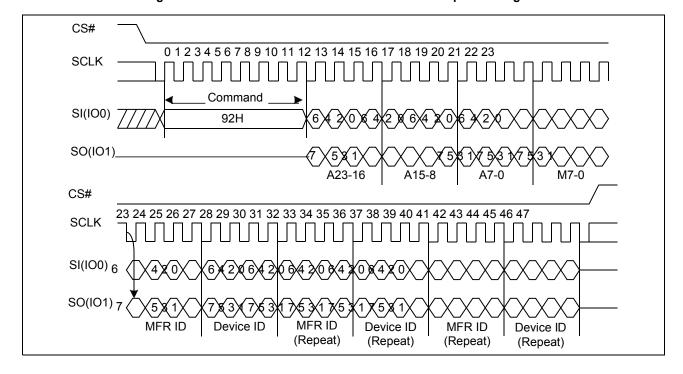
The Read Manufacturer/Device ID Dual I/O command is an alternative to the Release from Power-Down / Device ID command that provides both the JEDEC assigned Manufacturer ID and the specific Device ID by dual I/O.

The command is initiated by driving the CS# pin low and shifting the command code "92H" followed by a 24-bit address (A23-A0) of 000000H. After which, the Manufacturer ID and the Device ID are shifted out on the falling edge of SCLK with most significant bit (MSB) first as shown in Figure 26. If the 24-bit address is initially set to 000001H, the Device ID will be



GD25Q127C

Figure 26. Read Manufacture ID/ Device ID Dual I/O Sequence Diagram



7.24. Read Manufacture ID/ Device ID Quad I/O (94H)

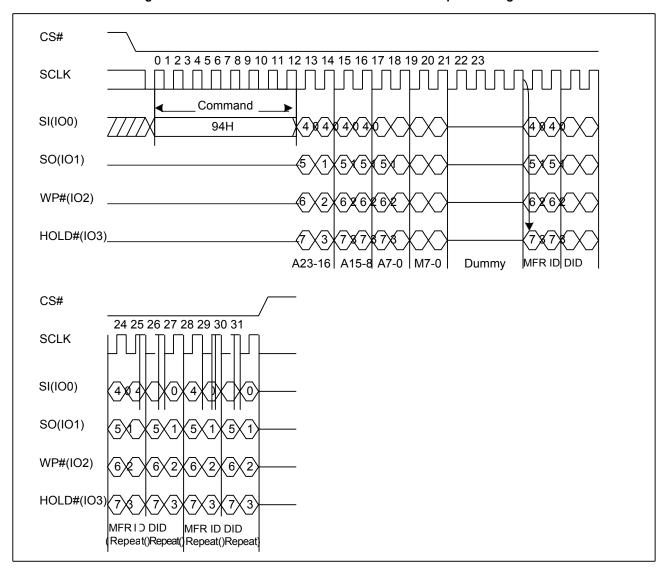
The Read Manufacturer/Device ID Quad I/O command is an alternative to the Release from Power-Down / Device ID command that provides both the JEDEC assigned Manufacturer ID and the specific Device ID by quad I/O.

The command is initiated by driving the CS# pin low and shifting the command code "94H" followed by a 24-bit address (A23-A0) of 000000H. After which, the Manufacturer ID and the Device ID are shifted out on the falling edge of SCLK with most significant bit (MSB) first as shown in Figure 27. If the 24-bit address is initially set to 000001H, the Device ID will be read first.



GD25Q127C

Figure 27. Read Manufacture ID/ Device ID Quad I/O Sequence Diagram



7.25. Read Identification (RDID) (9FH)

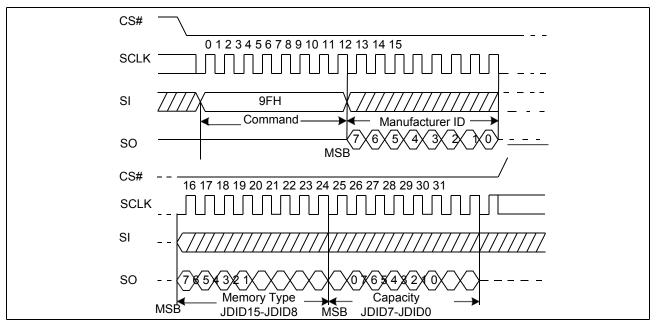
The Read Identification (RDID) command allows the 8-bit manufacturer identification to be read, followed by two bytes of device identification. The device identification indicates the memory type in the first byte, and the memory capacity of the device in the second byte. The Read Identification (RDID) command while an Erase or Program cycle is in progress is not decoded, and has no effect on the cycle that is in progress. The Read Identification (RDID) command should not be issued while the device is in Deep Power-Down Mode.

The device is first selected by driving CS# low. Then, the 8-bit command code for the command is shifted in. This is followed by the 24-bit device identification, stored in the memory. Each bit is shifted out on the falling edge of Serial Clock. The command sequence is shown in Figure 27. The Read Identification (RDID) command is terminated by driving CS# high at any time during data output. When CS# is driven high, the device is in the Standby Mode. Once in the Standby Mode, the device waits to be selected, so that it can receive, decode and execute commands.



GD25Q127C

Figure 28. Read Identification ID Sequence Diagram

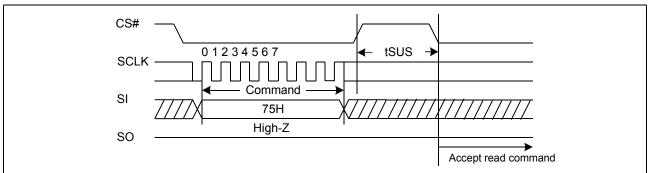


7.26. Program/Erase Suspend (PES) (75H)

The Program/Erase Suspend command "75H", allows the system to interrupt a page program or sector/block erase operation and then read data from any other sector or block. The Write Status Register command (01H/31H/11H) and Erase/Program Security Registers command (44H, 42H) and Erase commands (20H, 52H, D8H, C7H, 60H) and Page Program command (02H, 32H) are not allowed during Program suspend. The Write Status Register command (01H/31H/11H) and Erase Security Registers command (44H) and Erase commands (20H, 52H, D8H, C7H, 60H) are not allowed during Erase suspend. Program/Erase Suspend is valid only during the page program or sector/block erase operation. A maximum of time of "tsus" (See AC Characteristics) is required to suspend the program/erase operation.

The Program/Erase Suspend command will be accepted by the device only if the SUS2/SUS1 bit in the Status Register equal to 0 and WIP bit equal to 1 while a Page Program or a Sector or Block Erase operation is on-going. If the SUS2/SUS1 bit equal to 1 or WIP bit equal to 0, the Suspend command will be ignored by the device. The WIP bit will be cleared from 1 to 0 within "tsus" and the SUS2/SUS1 bit will be set from 0 to 1 immediately after Program/Erase Suspend. A power-off during the suspend period will reset the device and release the suspend state. The command sequence is show in Figure 29.

Figure 29. Program/Erase Suspend Sequence Diagram



GD25Q127C

7.27. Program/Erase Resume (PER) (7AH)

The Program/Erase Resume command must be written to resume the program or sector/block erase operation after a Program/Erase Suspend command. The Program/Erase command will be accepted by the device only if the SUS2/SUS1 bit equal to 1 and the WIP bit equal to 0. After issued the SUS2/SUS1 bit in the status register will be cleared from 1 to 0 immediately, the WIP bit will be set from 0 to 1 within 200ns and the Sector or Block will complete the erase operation or the page will complete the program operation. The Program/Erase Resume command will be ignored unless a Program/Erase Suspend is active. The command sequence is show in Figure 30.

SCLK 01234567
SCLK Command Command Resume Erase/Program

Figure 30. Program/Erase Resume Sequence Diagram

7.28. Erase Security Registers (44H)

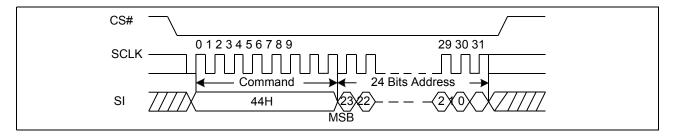
The GD25Q127C provides three 1024-byte Security Registers which can be erased and programmed individually. These registers may be used by the system manufacturers to store security and other important information separately from the main memory array.

The Erase Security Registers command is similar to Sector/Block Erase command. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit.

The Erase Security Registers command sequence: CS# goes low \rightarrow sending Erase Security Registers command \rightarrow CS# goes high. The command sequence is shown in Figure 31. CS# must be driven high after the eighth bit of the command code has been latched in; otherwise the Erase Security Registers command is not executed. As soon as CS# is driven high, the self-timed Erase Security Registers cycle (whose duration is t_{SE}) is initiated. While the Erase Security Registers cycle is in progress, the Status Register may be read to check the value of the Write in Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Erase Security Registers cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset. The Security Registers Lock Bit (LB3-1) in the Status Register can be used to OTP protect the security registers. Once the LB bit is set to 1, the Security Registers will be permanently locked; the Erase Security Registers command will be ignored.

Address	A23-16	A15-12	A11-10	A9-0
Security Register #1	00H	0001	0 0	Don't care
Security Register #2	00H	0010	0 0	Don't care
Security Register #3	00H	0011	0 0	Don't care

Figure 31. Erase Security Registers command Sequence Diagram



GD25Q127C

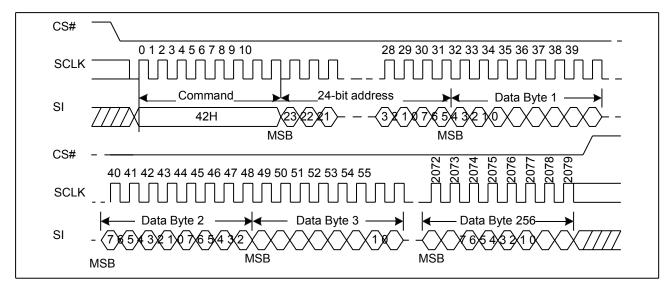
7.29. Program Security Registers (42H)

The Program Security Registers command is similar to the Page Program command. It allows from 1 to 1024 bytes Security Registers data to be programmed. A Write Enable (WREN) command must previously have been executed to set the Write Enable Latch (WEL) bit before sending the Program Security Registers command. The Program Security Registers command is entered by driving CS# Low, followed by the command code (42H), three address bytes and at least one data byte on SI. As soon as CS# is driven high, the self-timed Program Security Registers cycle (whose duration is tpp) is initiated. While the Program Security Registers cycle is in progress, the Status Register may be read to check the value of the Write in Progress (WIP) bit. The Write in Progress (WIP) bit is 1 during the self-timed Program Security Registers cycle, and is 0 when it is completed. At some unspecified time before the cycle is completed, the Write Enable Latch (WEL) bit is reset.

If the Security Registers Lock Bit (LB3-1) is set to 1, the Security Registers will be permanently locked. Program Security Registers command will be ignored.

Address	A23-16	A15-12	A11-10	A9-0
Security Register #1	00H	0001	0 0	Byte Address
Security Register #2	00H	0010	0 0	Byte Address
Security Register #3	00H	0011	0 0	Byte Address

Figure 32. Program Security Registers command Sequence Diagram



GD25Q127C

7.30. Read Security Registers (48H)

The Read Security Registers command is similar to Fast Read command. The command is followed by a 3-byte address (A23-A0) and a dummy byte, each bit being latched-in during the rising edge of SCLK. Then the memory content, at that address, is shifted out on SO, each bit being shifted out, at a Max frequency fC, during the falling edge of SCLK. The first byte addressed can be at any location. The address is automatically incremented to the next higher address after each byte of data is shifted out. Once the A9-A0 address reaches the last byte of the register (Byte 3FFH), it will reset to 000H, the command is completed by driving CS# high.

Address	A23-16	A15-12	A11-10	A9-0
Security Register #1	00H	0001	0 0	Byte Address
Security Register #2	00H	0010	0 0	Byte Address
Security Register #3	00H	0011	0 0	Byte Address

Figure 33. Read Security Registers command Sequence Diagram

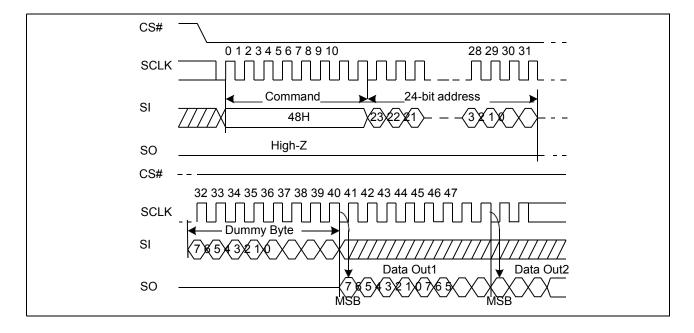
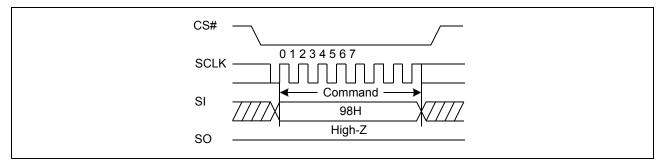


Figure 38. The Global Block/Sector Unlock Sequence Diagram



7.31. Enable Reset (66H) and Reset (99H)

If the Reset command is accepted, any on-going internal operation will be terminated and the device will return to its default power-on state and lose all the current volatile settings, such as Volatile Status Register bits, Write Enable Latch status (WEL), Program/Erase Suspend status, Read Parameter setting (P7-P0), Continuous Read Mode bit setting (M7-M0) and Wrap Bit Setting (W6-W4).

The "Enable Reset (66H)" and the "Reset (99H)" commands can be issued in either SPI mode. The "Reset (99H)"



GD25Q127C

command sequence as follow: CS# goes low \rightarrow Sending Enable Reset command \rightarrow CS# goes high \rightarrow CS# goes low \rightarrow Sending Reset command \rightarrow CS# goes high. Once the Reset command is accepted by the device, the device will take approximately t_{RST}/t_{RST_E} to reset. During this period, no command will be accepted. Data corruption may happen if there is an on-going or suspended internal Erase or Program operation when Reset command sequence is accepted by the device. It is recommended to check the BUSY bit and the SUS bit in Status Register before issuing the Reset command sequence.

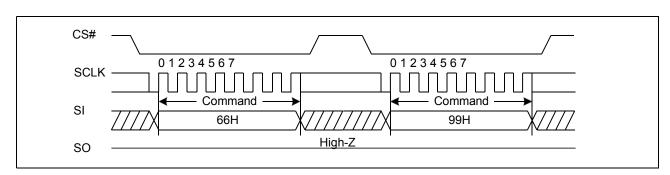


Figure 39. Enable Reset and Reset command Sequence Diagram

7.32. Read Unique ID (4BH)

The Read Unique ID command accesses a factory-set read-only 128bit number that is unique to each device. The Unique ID can be used in conjunction with user software methods to help prevent copying or cloning of a system.

The Read Unique ID command sequence: CS# goes low → sending Read Unique ID command → Dummy Byte1 → Dummy Byte3 → Dummy Byte4 → 128bit Unique ID Out → CS# goes high.

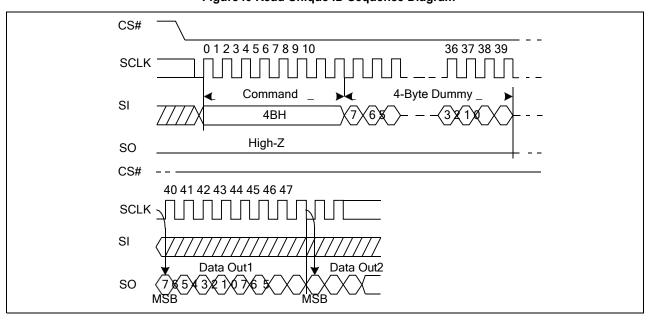


Figure 40 Read Unique ID Sequence Diagram



GD25Q127C

7.33. Read Serial Flash Discoverable Parameter (5AH)

The Serial Flash Discoverable Parameter (SFDP) standard provides a consistent method of describing the functional and feature capabilities of serial flash devices in a standard set of internal parameter tables. These parameter tables can be interrogated by host system software to enable adjustments needed to accommodate divergent features from multiple vendors. The concept is similar to the one found in the Introduction of JEDEC Standard, JESD68 on CFI. SFDP is a standard of JEDEC Standard No.216.

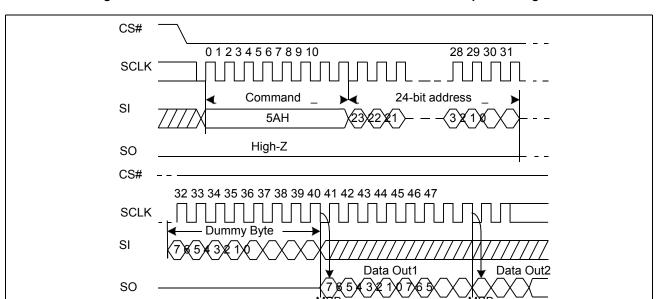


Figure 41. Read Serial Flash Discoverable Parameter command Sequence Diagram



Table 7.3. Signature and Parameter Identification Data Values

Description	Comment	Add(H)	DW Add	Data	Data
·		(Byte)	(Bit)		
SFDP Signature	Fixed:50444653H	00H	07:00	53H	53H
		01H	15:08	46H	46H
		02H	23:16	44H	44H
		03H	31:24	50H	50H
SFDP Minor Revision Number	Start from 00H	04H	07:00	00H	00H
SFDP Major Revision Number	Start from 01H	05H	15:08	01H	01H
Number of Parameters Headers	Start from 00H	06H	23:16	01H	01H
Unused	Contains 0xFFH and can never be changed	07H	31:24	FFH	FFH
ID number (JEDEC)	00H: It indicates a JEDEC specified header	08H	07:00	00H	00H
Parameter Table Minor Revision Number	Start from 0x00H	09H	15:08	00H	00H
Parameter Table Major Revision Number	Start from 0x01H	0AH	23:16	01H	01H
Parameter Table Length	How many DWORDs in the	0BH	31:24	09H	09H
(in double word)	Parameter table				
Parameter Table Pointer (PTP)	First address of JEDEC Flash	0CH	07:00	30H	30H
	Parameter table	0DH	15:08	00H	00H
		0EH	23:16	00H	00H
Unused	Contains 0xFFH and can never be changed	0FH	31:24	FFH	FFH
ID Number	It is indicates GigaDevice	10H	07:00	C8H	C8H
(GigaDevice Manufacturer ID)	manufacturer ID				
Parameter Table Minor Revision Number	Start from 0x00H	11H	15:08	00H	00H
Parameter Table Major Revision Number	Start from 0x01H	12H	23:16	01H	01H
Parameter Table Length	How many DWORDs in the	13H	31:24	03H	03H
(in double word)	Parameter table				
Parameter Table Pointer (PTP)	First address of GigaDevice Flash	14H	07:00	60H	60H
	Parameter table	15H	15:08	00H	00H
		16H	23:16	00H	00H
Unused	Contains 0xFFH and can never be	17H	31:24	FFH	FFH
	changed				



Table 7.4. Parameter Table (0): JEDEC Flash Parameter Tables

Description	Comment	Add(H)	DW Add	Data	Data
		(Byte)	(Bit)		
	00: Reserved; 01: 4KB erase;				
Block/Sector Erase Size	10: Reserved;		01:00	01b	
	11: not support 4KB erase				
Write Granularity	0: 1Byte, 1: 64Byte or larger		02	1b	•
Write Enable Instruction	0: Nonvolatile status bit				•
Requested for Writing to Volatile	1: Volatile status bit		03	0b	
Status Registers	(BP status register bit)	30H			E5H
	0: Use 50H Opcode,	3011			ESIT
Write Enable Opcode Select for	1: Use 06H Opcode,				
Writing to Volatile Status	Note: If target flash status register is		04	0b	
Registers	Nonvolatile, then bits 3 and 4 must				
	be set to 00b.				
Unused	Contains 111b and can never be		07:05	111b	
Onuscu	changed		07.00	1110	
4KB Erase Opcode		31H	15:08	20H	20H
(1-1-2) Fast Read	0=Not support, 1=Support		16	1b	
Address Bytes Number used in	00: 3Byte only, 01: 3 or 4Byte,		18:17	00b	
addressing flash array	10: 4Byte only, 11: Reserved			000	
Double Transfer Rate (DTR)	0=Not support, 1=Support		19	0b	
clocking	0-Not support, 1-Support	32H	13	0.0	F1H
(1-2-2) Fast Read	0=Not support, 1=Support		20	1b	
(1-4-4) Fast Read	0=Not support, 1=Support		21	1b	
(1-1-4) Fast Read	0=Not support, 1=Support		22	1b	
Unused			23	1b	
Unused		33H	31:24	FFH	FFH
Flash Memory Density		37H:34H	31:00	07FFFF	FFH
(1-4-4) Fast Read Number of Wait	0 0000b: Wait states (Dummy		04:00	00100b	
states	Clocks) not support	38H	04:00	001000	44H
(1-4-4) Fast Read Number of	000b:Mode Bits not support	300	07:05	010b	44 ⊓
Mode Bits	000b.Mode Bits not support		07.03	0100	
(1-4-4) Fast Read Opcode		39H	15:08	EBH	EBH
(1-1-4) Fast Read Number of Wait	0 0000b: Wait states (Dummy		20:16	01000b	
states	Clocks) not support	3AH	20.10	010000	08H
(1-1-4) Fast Read Number of	000b:Mode Bits not support	JAIT	23:21	000b	רוטט
Mode Bits	Todop.iviode bits flot support		۷.۷۱	0000	
(1-1-4) Fast Read Opcode		3BH	31:24	6BH	6BH



宇翔达 Dual and Qu	uad Seriai Flash		G	iD25Q12	<i>/</i> C
Description	Comment	Add(H) (Byte)	DW Add (Bit)	Data	Data
(1-1-2) Fast Read Number of Wait states	0 0000b: Wait states (Dummy Clocks) not support		04:00	01000b	
(1-1-2) Fast Read Number of Mode Bits	000b: Mode Bits not support	- 3CH	07:05	000b	08H
(1-1-2) Fast Read Opcode		3DH	15:08	3BH	3BH
(1-2-2) Fast Read Number of Wait states	0 0000b: Wait states (Dummy Clocks) not support	9511	20:16	00010b	1011
(1-2-2) Fast Read Number of Mode Bits	000b: Mode Bits not support	- 3EH	23:21	010b	- 42H
(1-2-2) Fast Read Opcode		3FH	31:24	ВВН	BBH
(2-2-2) Fast Read	0=not support 1=support		00	0b	
Unused		40H	03:01	111b	
(4-4-4) Fast Read	0=not support 1=support	7 400	04	0b	EEH
Unused		1	07:05	111b	
Unused		43H:41H	31:08	0xFFH	0xFFH
Unused		45H:44H	15:00	0xFFH	0xFFH
(2-2-2) Fast Read Number of Wait states	0 0000b: Wait states (Dummy Clocks) not support		20:16	00000b	- 00H
(2-2-2) Fast Read Number of Mode Bits	000b: Mode Bits not support	- 46H	23:21	000b	
(2-2-2) Fast Read Opcode		47H	31:24	FFH	FFH
Unused		49H:48H	15:00	0xFFH	0xFFH
(4-4-4) Fast Read Number of Wait states	0 0000b: Wait states (Dummy Clocks) not support	- 4AH	20:16	00000b	- 00H
(4-4-4) Fast Read Number of Mode Bits	000b: Mode Bits not support	7//11	23:21	000b	0011
(4-4-4) Fast Read Opcode		4BH	31:24	EBH	EBH
Sector Type 1 Size	Sector/block size=2^N bytes 0x00b: this sector type don't exist	4CH	07:00	0CH	0CH
Sector Type 1 erase Opcode		4DH	15:08	20H	20H
Sector Type 2 Size	Sector/block size=2^N bytes 0x00b: this sector type don't exist	4EH	23:16	0FH	0FH
Sector Type 2 erase Opcode		4FH	31:24	52H	52H
Sector Type 3 Size	Sector/block size=2^N bytes 0x00b: this sector type don't exist	50H	07:00	10H	10H
Sector Type 3 erase Opcode		51H	15:08	D8H	D8H
Sector Type 4 Size	Sector/block size=2^N bytes 0x00b: this sector type don't exist	52H	23:16	00H	00H
Sector Type 4 erase Opcode		53H	31:24	FFH	FFH



GD25Q127C

Table 7.5. Parameter Table (1): GigaDevice Flash Parameter Tables

Description	Comment	Add(H) (Byte)	DW Add (Bit)	Data	Data
Vcc Supply Maximum Voltage	2000H=2.000V 2700H=2.700V 3600H=3.600V	61H:60H	15:00	3600H	3600H
Vcc Supply Minimum Voltage	1650H=1.650V 2250H=2.250V 2350H=2.350V 2700H=2.700V	63H:62H	31:16	2700H	2700H
HW Reset# pin	0=not support 1=support		00	1b	
HW Hold# pin	0=not support 1=support		01	1b	
Deep Power Down Mode	0=not support 1=support		02	1b	
SW Reset	0=not support 1=support	_	03	1b	
SW Reset Opcode	Should be issue Reset Enable(66H) before Reset cmd.	65H:64H	11:04	1001 1001b (99H)	F99FH
Program Suspend/Resume	0=not support 1=support		12	1b	
Erase Suspend/Resume	0=not support 1=support		13	1b	
Unused			14	1b	
Wrap-Around Read mode	0=not support 1=support		15	1b	
Wrap-Around Read mode Opcode		66H	23:16	77H	77H
Wrap-Around Read data length	08H:support 8B wrap-around read 16H:8B&16B 32H:8B&16B&32B 64H:8B&16B&32B&64B	67H	31:24	64H	64H
Individual block lock	0=not support 1=support		00	0b	
Individual block lock bit (Volatile/Nonvolatile)	0=Volatile 1=Nonvolatile		01	0b	
Individual block lock Opcode			09:02	FFH	
Individual block lock Volatile protect bit default protect status	0=protect 1=unprotect	6BH:68H	10	0b	CBFC/ EBFCH
Secured OTP	0=not support 1=support		11	1b	(1)
Read Lock	0=not support 1=support		12	0b	
Permanent Lock	0=not support 1=support		13	0b/1b(1)	
Unused			15:14	11b	
Unused			31:16	FFFFH	FFFFH

NOTE:

(1) GD25Q127CxxSx support Permanent Lock. Please contact GigaDevice for details.

GD25Q127C

8. ELECTRICAL CHARACTERISTICS

8.1. POWER-ON TIMING

Figure 42. Power-on Timing Sequence Diagram

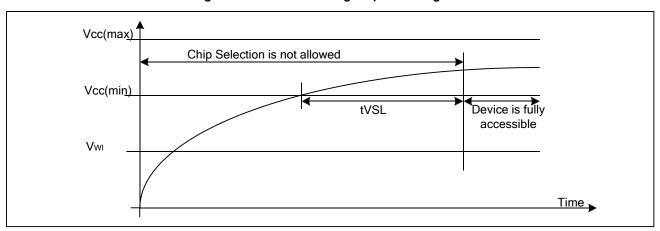


Table 8.1. Power-Up Timing and Write Inhibit Threshold

Symbol	Parameter	Min	Max	Unit
tVSL	VCC (min) To CS# Low	2.5		ms
VWI	Write Inhibit Voltage	1.5	2.5	V

8.2. INITIAL DELIVERY STATE

The device is delivered with the memory array erased: all bits are set to 1(each byte contains FFH). The Status Register bits are set to 0, except DRV1 bit (S22) is set to 1.

8.3. ABSOLUTE MAXIMUM RATINGS

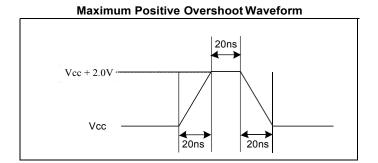
Parameter	Value	Unit
Ambient Operating Temperature	-40 to 85	
	-40 to 105	°C
	-40 to 125	
Storage Temperature	-65 to 150	°C
Applied Input/Output Voltage	-0.6 to VCC+0.4	V
Transient Input/Output Voltage (note: overshoot)	-2.0 to VCC+2.0	V
VCC	-0.6 to 4.2	V



GD25Q127C

Figure 43. Maximum Negative/positive Overshoot Diagram

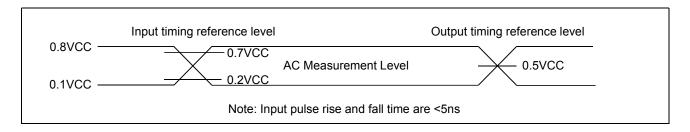
Vss-2.0V 20ns 20ns 20ns 20ns



8.4. CAPACITANCE MEASUREMENT CONDITIONS

Symbol	Parameter	Min	Тур.	Max	Unit	Conditions
CIN	Input Capacitance			6	pF	VIN=0V
COUT	Output Capacitance			8	pF	VOUT=0V
CL	Load Capacitance	30		pF		
	Input Rise And Fall time			5	ns	
	Input Pulse Voltage	0.1VC	C to 0.8V0	CC	V	
	Input Timing Reference Voltage	0.2VCC to 0.7VCC		V		
	Output Timing Reference Voltage	0.5VCC		V		

Figure 44. Input Test Waveform and Measurement Level





GD25Q127C

8.5. DC CHARACTERISTICS

(T= -40°C~85°C, VCC=2.7~3.6V, Normal Mode)

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit.					
lu	Input Leakage Current				±2	μA					
ILO	Output Leakage Current				±2	μΑ					
Icc1	Standby Current	CS#=VCC,		20	50	μΑ					
		V _{IN} =VCC or VSS									
I _{CC2}	Deep Power-Down Current	CS#=VCC,		1	5	μA					
		V _{IN} =VCC or VSS									
		CLK=0.1VCC /									
		0.9VCC		15	20	mA					
		at 104MHz,			15 2	15	15	15	15	15	20
Іссз	Operating Current (Read)	Q=Open(*1,*2,*4 I/O)			18						
ICC3	Operating Current (Read)	CLK=0.1VCC /									
		0.9VCC		13	10	mA					
		at 80MHz,		13	10	"					
		Q=Open(*1,*2,*4 I/O)									
I _{CC4}	Operating Current (PP)	CS#=VCC			27	mA					
I _{CC5}	Operating Current (WRSR)	CS#=VCC			27	mA					
I _{CC6}	Operating Current (SE)	CS#=VCC			27	mA					
Icc7	Operating Current (BE)	CS#=VCC			27	mA					
I _{CC8}	Operating Current (CE)	CS#=VCC			27	mA					
VıL	Input Low Voltage				0.2VCC	V					
V _{IH}	Input High Voltage		0.7VCC		VCC+0.4	V					
V _{OL}	Output Low Voltage	I _{OL} =100μA			0.2	V					
V _{OH}	Output High Voltage	I _{OH} =-100μA	VCC-0.2			V					

^{1.} Typical value tested at T = 25° C.

^{2.} Value guaranteed by design and/or characterization, not 100% tested in production.



GD25Q127C

(T= -40°C~85°C, VCC=2.7~3.6V, Low Power Mode)

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit.
lμ	Input Leakage Current				±2	μΑ
I _{LO}	Output Leakage Current				±2	μA
Icc1	Standby Current	CS#=VCC,		20	50	μΑ
		V _{IN} =VCC or VSS				
Icc2	Deep Power-Down Current	CS#=VCC,		1	5	μΑ
		V _{IN} =VCC or VSS				
		CLK=0.1VCC /				
		0.9VCC		13	20	^
		at 104MHz,				mA
	Operating Comment (Deed)	Q=Open(*1,*2,*4 I/O)				
Icc3	Operating Current (Read)	CLK=0.1VCC /				
		0.9VCC		10	40	
		at 80MHz,		10	18	mA
		Q=Open(*1,*2,*4 I/O)				
Icc4	Operating Current (PP)	CS#=VCC			25	mA
Icc5	Operating Current (WRSR)	CS#=VCC			25	mA
Icc6	Operating Current (SE)	CS#=VCC			25	mA
Icc7	Operating Current (BE)	CS#=VCC			25	mA
Icc8	Operating Current (CE)	CS#=VCC			25	mA
VıL	Input Low Voltage				0.2VCC	V
VIH	Input High Voltage		0.7VCC		VCC+0.4	V
Vol	Output Low Voltage	I _{OL} =100μA			0.2	V
V _{OH}	Output High Voltage	I _{OH} =-100μA	VCC-0.2			V

- 1. Typical value tested at T = 25° C.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



GD25Q127C

(T= -40°C~105°C, VCC=2.7~3.6V, Normal Mode)

Symbol	Parameter	Test Condition	Min.	Тур	Max.	Unit.
ILI	Input Leakage Current				±2	μΑ
I _{LO}	Output Leakage Current				±2	μΑ
Icc1	Standby Current	CS#=VCC,		20	100	μΑ
		V _{IN} =VCC or VSS				
Icc2	Deep Power-Down Current	CS#=VCC,		1	20	μA
		V _{IN} =VCC or VSS				
		CLK=0.1VCC /				
		0.9VCC		15	20	m Λ
		at 80MHz,		15	20	mA
	On a ratio a Commant (Dand)	Q=Open(*1,*2,*4 I/O)				
Іссз	Operating Current (Read)	CLK=0.1VCC /				
		0.9VCC		13	18	
		at 60MHz,		13	10	mA
		Q=Open(*1,*2,*4 I/O)				
Icc4	Operating Current (PP)	CS#=VCC			30	mA
Icc5	Operating Current(WRSR)	CS#=VCC			30	mA
Icc6	Operating Current (SE)	CS#=VCC			30	mA
Icc7	Operating Current (BE)	CS#=VCC			30	mA
Icc8	Operating Current (CE)	CS#=VCC			30	mA
VIL	Input Low Voltage				0.2VCC	V
VIH	Input High Voltage		0.7VCC		VCC+0.4	V
Vol	Output Low Voltage	I _{OL} =100μA			0.2	V
V _{OH}	Output High Voltage	I _{OH} =-100μA	VCC-0.2			V

- 1. Typical value tested at T = 25° C.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



GD25Q127C

(T= -40°C~105°C, VCC=2.7~3.6V, Low Power Mode)

Symbol	Parameter	Test Condition	Min.	Тур	Max.	Unit.					
lы	Input Leakage Current				±2	μA					
I _{LO}	Output Leakage Current				±2	μA					
Icc ₁	Standby Current	CS#=VCC,		20	100	μA					
		V _{IN} =VCC or VSS									
Icc2	Deep Power-Down Current	CS#=VCC,		1	20	μA					
		V _{IN} =VCC or VSS									
		CLK=0.1VCC /									
		0.9VCC		12	20	m A					
		at 80MHz,		13	13	13	13	13	13	20	mA
I _{CC3}	Operating Current (Read)	Q=Open(*1,*2,*4 I/O)									
ICC3	Operating Current (Read)	CLK=0.1VCC /									
		0.9VCC		10	18	mΛ					
		at 60MHz,		10	10	mA					
		Q=Open(*1,*2,*4 I/O)									
I _{CC4}	Operating Current (PP)	CS#=VCC			25	mA					
I _{CC5}	Operating Current(WRSR)	CS#=VCC			25	mA					
Icc6	Operating Current (SE)	CS#=VCC			25	mA					
Icc7	Operating Current (BE)	CS#=VCC			25	mA					
Icc8	Operating Current (CE)	CS#=VCC			25	mA					
VIL	Input Low Voltage				0.2VCC	V					
VIH	Input High Voltage		0.7VCC		VCC+0.4	V					
Vol	Output Low Voltage	I _{OL} =100μA			0.2	V					
V _{OH}	Output High Voltage	I _{OH} =-100μA	VCC-0.2			V					

- 1. Typical value tested at T = 25℃.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



GD25Q127C

(T= -40°C~125°C, VCC=2.7~3.6V, Normal Mode)

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit.			
lц	Input Leakage Current				±2	μA			
I _{LO}	Output Leakage Current				±2	μA			
Icc1	Standby Current	CS#=VCC,		20	120	μA			
		V _{IN} =VCC or VSS							
I _{CC2}	Deep Power-Down Current	CS#=VCC,		1	25	μA			
		V _{IN} =VCC or VSS							
		CLK=0.1VCC /							
		0.9VCC		15	20				
		at 80MHz,		15	15	15	15	20	mA
	Operation Comment (Deed)	Q=Open(*1,*2,*4 I/O)							
Icc3	Operating Current (Read)	CLK=0.1VCC /							
		0.9VCC		40	18				
		at 60MHz,		13	10	mA			
		Q=Open(*1,*2,*4 I/O)							
Icc4	Operating Current (PP)	CS#=VCC			30	mA			
Icc5	Operating Current (WRSR)	CS#=VCC			30	mA			
Icc6	Operating Current (SE)	CS#=VCC			30	mA			
I _{CC7}	Operating Current (BE)	CS#=VCC			30	mA			
Icc8	Operating Current (CE)	CS#=VCC			30	mA			
VIL	Input Low Voltage				0.2VCC	V			
VIH	Input High Voltage		0.7VCC		VCC+0.4	V			
VoL	Output Low Voltage	I _{OL} =100μA			0.2	V			
V _{OH}	Output High Voltage	I _{OH} =-100μA	VCC-0.2			V			

- 1. Typical value tested at T = 25° C.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



GD25Q127C

(T= -40°C~125°C, VCC=2.7~3.6V, Low Power Mode)

Symbol	Parameter	Test Condition	Min.	Тур.	Max.	Unit.	
lц	Input Leakage Current				±2	μΑ	
I _{LO}	Output Leakage Current				±2	μΑ	
Icc1	Standby Current	CS#=VCC,		20	120	μA	
		V _{IN} =VCC or VSS					
Icc2	Deep Power-Down Current	CS#=VCC,		1	25	μA	
		V _{IN} =VCC or VSS					
		CLK=0.1VCC /					
		0.9VCC		12	20	^	
		at 80MHz,		13	13	20	mA
	On a ratio a Commant (Dand)	Q=Open(*1,*2,*4 I/O)					
Icc3	Operating Current (Read)	CLK=0.1VCC /					
		0.9VCC		10	18	^	
		at 60MHz,		10	10	mA	
		Q=Open(*1,*2,*4 I/O)					
Icc4	Operating Current (PP)	CS#=VCC			25	mA	
Icc5	Operating Current (WRSR)	CS#=VCC			25	mA	
Icc6	Operating Current (SE)	CS#=VCC			25	mA	
Icc7	Operating Current (BE)	CS#=VCC			25	mA	
Icc8	Operating Current (CE)	CS#=VCC			25	mA	
VIL	Input Low Voltage				0.2VCC	V	
VIH	Input High Voltage		0.7VCC		VCC+0.4	V	
Vol	Output Low Voltage	I _{OL} =100μA			0.2	V	
V _{OH}	Output High Voltage	I _{OH} =-100μA	VCC-0.2			V	

- 1. Typical value tested at T = 25° C.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



GD25Q127C

8.6. AC CHARACTERISTICS

(T= -40°C~85°C, VCC=2.7~3.6V, C_L=30pf, Normal Mode)

Symbol	Parameter	Min.	Тур.	Max.	Unit.
F	Serial Clock Frequency For: Fast Read (0BH), on 2.7V-3.6V			104	NAL 1-
Fc	power supply			104	MHz
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C1}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			80	MHz
	Read (E7H), on 2.7V-3.0V power supply				
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C2}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			104	MHz
	Read (E7H), on 3.0V-3.6V power supply				
f_R	Serial Clock Frequency For: Read (03H), Read Manufacturer			80	MHz
ıк	ID/device ID (90H), Read Identification (9FH)			00	IVII IZ
tсьн	Serial Clock High Time	4.5			ns
t _{CLL}	Serial Clock Low Time	4.5			ns
t clch	Serial Clock Rise Time (Slew Rate)	0.1			V/ns
t chcl	Serial Clock Fall Time (Slew Rate)	0.1			V/ns
tslcн	CS# Active Setup Time	5			ns
tснsн	CS# Active Hold Time	5			ns
tsнсн	CS# Not Active Setup Time	5			ns
t chsl	CS# Not Active Hold Time	5			ns
t _{SHSL}	CS# High Time (Read/Write)	20			ns
tshqz	Output Disable Time			6	ns
t _{CLQX}	Output Hold Time	1.0			ns
t DVCH	Data In Setup Time	2			ns
t _{CHDX}	Data In Hold Time	2			ns
thlch	HOLD# Low Setup Time (Relative To Clock)	5			ns
tннсн	HOLD# High Setup Time (Relative To Clock)	5			ns
t _{CHHL}	HOLD# High Hold Time (Relative To Clock)	5			ns
tсннн	HOLD# Low Hold Time (Relative To Clock)	5			ns
tHLQZ	HOLD# Low To High-Z Output			6	ns
tннqх	HOLD# Low To Low-Z Output			6	ns
t _{CLQV}	Clock Low To Output Valid			6.5	ns
twhsl	Write Protect Setup Time Before CS# Low	20			ns
tshwL	Write Protect Hold Time After CS# High	100			ns
t _{DP}	CS# High To Deep Power-Down Mode			20	μs
	CS# High To Standby Mode Without Electronic Signature				† ·
t RES1	Read			30	μs
t _{RES2}	CS# High To Standby Mode With Electronic Signature Read			30	μs
t _{sus}	CS# High To Next Command After Suspend			20	μs
t _{RS}	Latency Between Resume And Next Suspend	100			μs



GD25Q127C

t RST	CS# High To Next Command After Reset (Except From Erase)		30	μs
t _{RST_E}	CS# High To Next Command After Reset (From Erase)		12	ms
tw	Write Status Register Cycle Time	5	30	ms
t _{BP1}	Byte Program Time (First Byte)	30	50	μs
t _{BP2}	Additional Byte Program Time (After First Byte)	2.5	12	μs
t PP	Page Programming Time	0.5	2.4	ms
t _{SE}	Sector Erase Time	50	400	ms
t _{BE1}	Block Erase Time (32K Bytes)	0.16	0.8	S
t _{BE2}	Block Erase Time (64K Bytes)	0.3	1.2	S
tce	Chip Erase Time (GD25Q127C)	50	120	S

- 1. Typical value tested at $T = 25^{\circ}C$.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



GD25Q127C

(T= -40°C~85°C, VCC=2.7~3.6V, C_L=30pf, Low Power Mode)

Symbol	Parameter	Min.	Тур.	Max.	Unit.
Fc	Serial Clock Frequency For: Fast Read (0BH), on 2.7V-3.6V			104	MHz
rc .	power supply			104	IVITIZ
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C1}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			80	MHz
	Read (E7H), on 2.7V-3.0V power supply				
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C2}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			104	MHz
	Read (E7H), on 3.0V-3.6V power supply				
f _R	Serial Clock Frequency For: Read (03H), Read Manufacturer			80	MHz
IK	ID/device ID (90H), Read Identification (9FH)			00	IVII IZ
t clh	Serial Clock High Time	4.5			ns
t _{CLL}	Serial Clock Low Time	4.5			ns
t clch	Serial Clock Rise Time (Slew Rate)	0.1			V/ns
tchcl	Serial Clock Fall Time (Slew Rate)	0.1			V/ns
t slch	CS# Active Setup Time	5			ns
t _{CHSH}	CS# Active Hold Time	5			ns
t shch	CS# Not Active Setup Time	5			ns
t _{CHSL}	CS# Not Active Hold Time	5			ns
t shsl	CS# High Time (Read/Write)	20			ns
t shqz	Output Disable Time			6	ns
t _{CLQX}	Output Hold Time	1.0			ns
tovcн	Data In Setup Time	2			ns
t _{CHDX}	Data In Hold Time	2			ns
thlch	HOLD# Low Setup Time (Relative To Clock)	5			ns
tннсн	HOLD# High Setup Time (Relative To Clock)	5			ns
t CHHL	HOLD# High Hold Time (Relative To Clock)	5			ns
tсннн	HOLD# Low Hold Time (Relative To Clock)	5			ns
thlqz	HOLD# Low To High-Z Output			6	ns
tннqх	HOLD# Low To Low-Z Output			6	ns
tclqv	Clock Low To Output Valid			6.5	ns
twhsl	Write Protect Setup Time Before CS# Low	20			ns
t _{SHWL}	Write Protect Hold Time After CS# High	100			ns
t _{DP}	CS# High To Deep Power-Down Mode			50	μs
	CS# High To Standby Mode Without Electronic Signature				1 1
t _{RES1}	Read			50	μs
t _{RES2}	CS# High To Standby Mode With Electronic Signature Read			50	μs
tsus	CS# High To Next Command After Suspend			50	μs
t _{RS}	Latency Between Resume And Next Suspend	100			μs
trst	CS# High To Next Command After Reset (Except From	100			μο
61.01	Erase)			50	μs



GD25Q127C

t _{RST_E}	CS# High To Next Command After Reset (From Erase)		30	ms
tw	Write Status Register Cycle Time	15	80	ms
t _{BP1}	Byte Program Time (First Byte)	60	150	μs
t _{BP2}	Additional Byte Program Time (After First Byte)	8	40	μs
tpp	Page Programming Time	1.6	5	ms
tse	Sector Erase Time	100	600	ms
t _{BE1}	Block Erase Time (32K Bytes)	0.3	1.4	S
t _{BE2}	Block Erase Time (64K Bytes)	0.5	2.6	S
tce	Chip Erase Time (GD25Q127C)	150	300	S

- 1. Typical value tested at T = 25° C.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



GD25Q127C

(T= -40°C~105°C, VCC=2.7~3.6V, C_L=30pf, Normal Mode)

Symbol	Parameter	Min.	Тур.	Max.	Unit.	
Fc	Serial Clock Frequency For: Fast Read (0BH), on 2.7V-3.6V			104	MHz	
ГС	power supply			104	IVITIZ	
	Serial Clock Frequency For: Dual Output (3BH), Quad Output					
f _{C1}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			70	MHz	
	Read (E7H), on 2.7V-3.0V power supply					
	Serial Clock Frequency For: Dual Output (3BH), Quad Output					
f _{C2}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			80	MHz	
	Read (E7H), on 3.0V-3.6V power supply					
f _R	Serial Clock Frequency For: Read (03H), Read Manufacturer			60	MHz	
IK	ID/device ID (90H), Read Identification (9FH)			00	IVII IZ	
tсьн	Serial Clock High Time	4.5			ns	
t _{CLL}	Serial Clock Low Time	4.5			ns	
tсьсн	Serial Clock Rise Time (Slew Rate)	0.1			V/ns	
t _{CHCL}	Serial Clock Fall Time (Slew Rate)	0.1			V/ns	
t slch	CS# Active Setup Time	5			ns	
t _{CHSH}	CS# Active Hold Time	5			ns	
tshch	CS# Not Active Setup Time	5			ns	
t _{CHSL}	CS# Not Active Hold Time	5			ns	
t shsl	CS# High Time (Read/Write)	20			ns	
t shqz	Output Disable Time			6	ns	
t _{CLQX}	Output Hold Time	1.0			ns	
tоvсн	Data In Setup Time	2			ns	
t _{CHDX}	Data In Hold Time	2			ns	
thlch	HOLD# Low Setup Time (Relative To Clock)	5			ns	
tннсн	HOLD# High Setup Time (Relative To Clock)	5			ns	
tсннL	HOLD# High Hold Time (Relative To Clock)	5			ns	
tсннн	HOLD# Low Hold Time (Relative To Clock)	5			ns	
thlaz	HOLD# Low To High-Z Output			6	ns	
tннqх	HOLD# Low To Low-Z Output			6	ns	
tclqv	Clock Low To Output Valid			7	ns	
twhsl	Write Protect Setup Time Before CS# Low	20			ns	
t _{SHWL}	Write Protect Hold Time After CS# High	100			ns	
t _{DP}	CS# High To Deep Power-Down Mode			20	μs	
-21	CS# High To Standby Mode Without Electronic Signature					
t _{RES1}	Read			30	μs	
t _{RES2}	CS# High To Standby Mode With Electronic Signature Read			30	μs	
tsus	CS# High To Next Command After Suspend			20	μs	
t _{RS}	Latency Between Resume And Next Suspend	100			μs	
ino	CS# High To Next Command After Reset (Except From	100			μο	
t RST	Erase)			30	μs	



GD25Q127C

t _{RST_E}	CS# High To Next Command After Reset (From Erase)		12	ms
tw	Write Status Register Cycle Time	5	30	ms
t _{BP1}	Byte Program Time (First Byte)	30	60	μs
t _{BP2}	Additional Byte Program Time (After First Byte)	2.5	15	μs
t PP	Page Programming Time	0.5	4	ms
tse	Sector Erase Time	50	400	ms
t _{BE}	Block Erase Time (32K Bytes)	0.16	2	S
t _{BE}	Block Erase Time (64K Bytes)	0.3	3	S
tce	Chip Erase Time (GD25Q127C)	50	150	S

- 1. Typical value tested at $T = 25^{\circ}C$.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



GD25Q127C

(T= -40°C~105°C, VCC=2.7~3.6V, C_L=30pf, Low Power Mode)

Symbol	Parameter	Min.	Тур.	Max.	Unit.
Fc	Serial Clock Frequency For: Fast Read (0BH), on 2.7V-3.6V			104	MHz
FC	power supply			104	IVIITZ
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f_{C1}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			70	MHz
	Read (E7H), on 2.7V-3.0V power supply				
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C2}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			80	MHz
	Read (E7H), on 3.0V-3.6V power supply				
f_{R}	Serial Clock Frequency For: Read (03H), Read Manufacturer			60	MHz
IK .	ID/device ID (90H), Read Identification (9FH)				1711 12
t clh	Serial Clock High Time	4.5			ns
t _{CLL}	Serial Clock Low Time	4.5			ns
t clch	Serial Clock Rise Time (Slew Rate)	0.1			V/ns
t _{CHCL}	Serial Clock Fall Time (Slew Rate)	0.1			V/ns
tslch	CS# Active Setup Time	5			ns
t _{CHSH}	CS# Active Hold Time	5			ns
t shch	CS# Not Active Setup Time	5			ns
t _{CHSL}	CS# Not Active Hold Time	5			ns
tshsl	CS# High Time (Read/Write)	20			ns
tsнqz	Output Disable Time			6	ns
t _{CLQX}	Output Hold Time	1.0			ns
t DVCH	Data In Setup Time	2			ns
t _{CHDX}	Data In Hold Time	2			ns
thlch	HOLD# Low Setup Time (Relative To Clock)	5			ns
tннсн	HOLD# High Setup Time (Relative To Clock)	5			ns
tchhl	HOLD# High Hold Time (Relative To Clock)	5			ns
tсннн	HOLD# Low Hold Time (Relative To Clock)	5			ns
t _{HLQZ}	HOLD# Low To High-Z Output			6	ns
thhqx	HOLD# Low To Low-Z Output			6	ns
tclqv	Clock Low To Output Valid			7	ns
twhsl	Write Protect Setup Time Before CS# Low	20			ns
t _{SHWL}	Write Protect Hold Time After CS# High	100			ns
t _{DP}	CS# High To Deep Power-Down Mode			50	μs
	CS# High To Standby Mode Without Electronic Signature			_	† •
t _{RES1}	Read			50	μs
t _{RES2}	CS# High To Standby Mode With Electronic Signature Read			50	μs
tsus	CS# High To Next Command After Suspend			50	μs
t _{RS}	Latency Between Resume And Next Suspend	100			μs
	CS# High To Next Command After Reset (Except From				F
t RST	Erase)			50	μs



GD25Q127C

t _{RST_E}	CS# High To Next Command After Reset (From Erase)		30	ms
tw	Write Status Register Cycle Time	15	80	ms
t _{BP1}	Byte Program Time (First Byte)	60	180	μs
t _{BP2}	Additional Byte Program Time (After First Byte)	8	50	μs
t _{PP}	Page Programming Time	1.6	6	ms
tse	Sector Erase Time	100	600	ms
t _{BE}	Block Erase Time (32K Bytes)	0.3	3	s
tвЕ	Block Erase Time (64K Bytes)	0.5	4	S
tce	Chip Erase Time (GD25Q127C)	150	360	S

- 1. Typical value tested at $T = 25^{\circ}C$.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



GD25Q127C

(T= -40°C~125°C, VCC=2.7~3.6V, C_L=30pf, Normal Mode)

Symbol	Parameter	Min.	Тур.	Max.	Unit.
Fc	Serial Clock Frequency For: Fast Read (0BH), on 2.7V-3.6V			104	MHz
C	power supply			104	IVII IZ
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C1}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			70	MHz
	Read (E7H), on 2.7V-3.0V power supply				
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C2}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			80	MHz
	Read (E7H), on 3.0V-3.6V power supply				
f _R	Serial Clock Frequency For: Read (03H), Read Manufacturer			60	MHz
110	ID/device ID (90H), Read Identification (9FH)				1411 12
t clh	Serial Clock High Time	4.5			ns
t _{CLL}	Serial Clock Low Time	4.5			ns
t clch	Serial Clock Rise Time (Slew Rate)	0.1			V/ns
tchcl	Serial Clock Fall Time (Slew Rate)	0.1			V/ns
t slch	CS# Active Setup Time	5			ns
t _{CHSH}	CS# Active Hold Time	5			ns
t shch	CS# Not Active Setup Time	5			ns
t _{CHSL}	CS# Not Active Hold Time	5			ns
tshsl	CS# High Time (Read/Write)	20			ns
t shqz	Output Disable Time			6	ns
t _{CLQX}	Output Hold Time	1.0			ns
t DVCH	Data In Setup Time	2			ns
t _{CHDX}	Data In Hold Time	3			ns
thlch	HOLD# Low Setup Time (Relative To Clock)	5			ns
tннсн	HOLD# High Setup Time (Relative To Clock)	5			ns
tchhl	HOLD# High Hold Time (Relative To Clock)	5			ns
tсннн	HOLD# Low Hold Time (Relative To Clock)	5			ns
thlqz	HOLD# Low To High-Z Output			6	ns
t HHQX	HOLD# Low To Low-Z Output			6	ns
tclqv	Clock Low To Output Valid			7	ns
twhsl	Write Protect Setup Time Before CS# Low	20			ns
t _{SHWL}	Write Protect Hold Time After CS# High	100			ns
t _{DP}	CS# High To Deep Power-Down Mode			20	μs
	CS# High To Standby Mode Without Electronic Signature				<u> </u>
t _{RES1}	Read			30	μs
t _{RES2}	CS# High To Standby Mode With Electronic Signature Read			30	μs
tsus	CS# High To Next Command After Suspend			20	μs
t _{RS}	Latency Between Resume And Next Suspend	100			μs
	CS# High To Next Command After Reset (Except From				1
t RST	Erase)			30	μs



GD25Q127C

t _{RST_E}	CS# High To Next Command After Reset (From Erase)		12	ms
tw	Write Status Register Cycle Time	5	30	ms
t _{BP1}	Byte Program Time (First Byte)	30	60	μs
t _{BP2}	Additional Byte Program Time (After First Byte)	2.5	15	μs
t _{PP}	Page Programming Time	0.5	4	ms
tse	Sector Erase Time	50	500	ms
t _{BE1}	Block Erase Time (32K Bytes)	0.16	2.5	S
t _{BE2}	Block Erase Time (64K Bytes)	0.3	4	S
tce	Chip Erase Time (GD25Q127C)	50	180	S

- 1. Typical value tested at $T = 25^{\circ}C$.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



GD25Q127C

(T= -40°C~125°C, VCC=2.7~3.6V, C_L=30pf, Low Power Mode)

Symbol	Parameter	Min.	Тур.	Max.	Unit.
Fc	Serial Clock Frequency For: Fast Read (0BH), on 2.7V-3.6V			104	MHz
FC	power supply			104	IVIITZ
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f_{C1}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			70	MHz
	Read (E7H), on 2.7V-3.0V power supply				
	Serial Clock Frequency For: Dual Output (3BH), Quad Output				
f _{C2}	(6BH), Dual I/O (BBH), Quad I/O (EBH), Quad I/O Word Fast			80	MHz
	Read (E7H), on 3.0V-3.6V power supply				
f_{R}	Serial Clock Frequency For: Read (03H), Read Manufacturer			60	MHz
IK	ID/device ID (90H), Read Identification (9FH)			00	IVII IZ
t clh	Serial Clock High Time	4.5			ns
t_{CLL}	Serial Clock Low Time	4.5			ns
t clch	Serial Clock Rise Time (Slew Rate)	0.1			V/ns
t _{CHCL}	Serial Clock Fall Time (Slew Rate)	0.1			V/ns
t slch	CS# Active Setup Time	5			ns
t _{CHSH}	CS# Active Hold Time	5			ns
tsнсн	CS# Not Active Setup Time	5			ns
t _{CHSL}	CS# Not Active Hold Time	5			ns
t shsl	CS# High Time (Read/Write)	20			ns
t shqz	Output Disable Time			6	ns
t _{CLQX}	Output Hold Time	1.0			ns
t _{DVCH}	Data In Setup Time	2			ns
t _{CHDX}	Data In Hold Time	3			ns
thlch	HOLD# Low Setup Time (Relative To Clock)	5			ns
tннсн	HOLD# High Setup Time (Relative To Clock)	5			ns
tchhl	HOLD# High Hold Time (Relative To Clock)	5			ns
tсннн	HOLD# Low Hold Time (Relative To Clock)	5			ns
t HLQZ	HOLD# Low To High-Z Output			6	ns
tннqх	HOLD# Low To Low-Z Output			6	ns
tclqv	Clock Low To Output Valid			7	ns
twhsl	Write Protect Setup Time Before CS# Low	20			ns
t _{SHWL}	Write Protect Hold Time After CS# High	100			ns
t _{DP}	CS# High To Deep Power-Down Mode			50	μs
	CS# High To Standby Mode Without Electronic Signature				† •
t _{RES1}	Read			50	μs
t _{RES2}	CS# High To Standby Mode With Electronic Signature Read			50	μs
tsus	CS# High To Next Command After Suspend			50	μs
t _{RS}	Latency Between Resume And Next Suspend	100			μs
trst	CS# High To Next Command After Reset (Except From				F
-1101	Erase)			50	μs



GD25Q127C

t _{RST_E}	CS# High To Next Command After Reset (From Erase)		30	ms
tw	Write Status Register Cycle Time	15	80	ms
t _{BP1}	Byte Program Time (First Byte)	60	180	μs
t _{BP2}	Additional Byte Program Time (After First Byte)	8	50	μs
tpp	Page Programming Time	1.6	6	ms
tse	Sector Erase Time	100	600	ms
t _{BE1}	Block Erase Time (32K Bytes)	0.3	4	S
t _{BE2}	Block Erase Time (64K Bytes)	0.5	5	S
tce	Chip Erase Time (GD25Q127C)	150	400	S

- 1. Typical value tested at T = 25° C.
- 2. Value guaranteed by design and/or characterization, not 100% tested in production.



GD25Q127C

Figure 45. Serial Input Timing

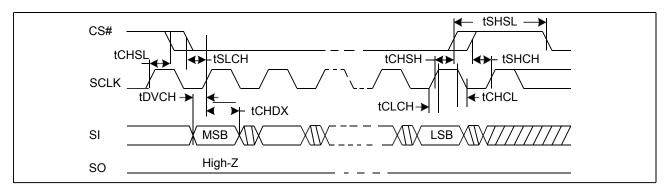


Figure 46. Output Timing

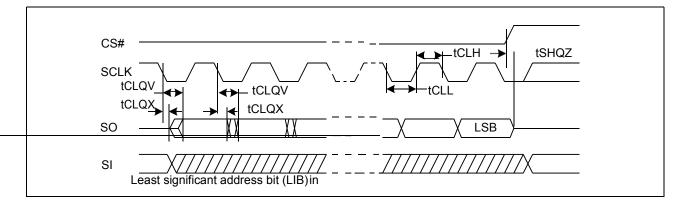


Figure 47. Resume to Suspend Timing Diagram

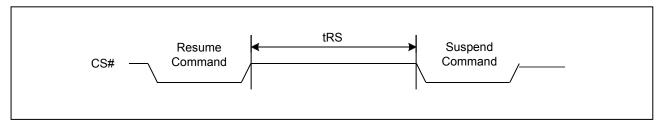
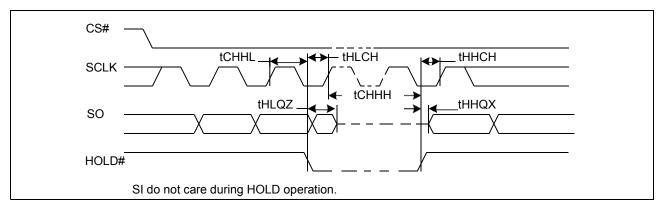


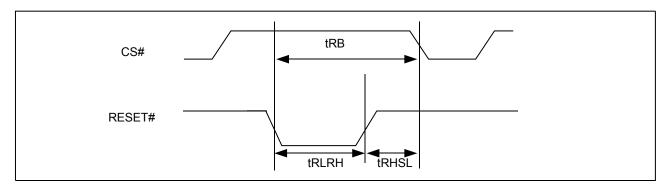
Figure 48. Hold Timing





GD25Q127C

Figure 49. RESET Timing

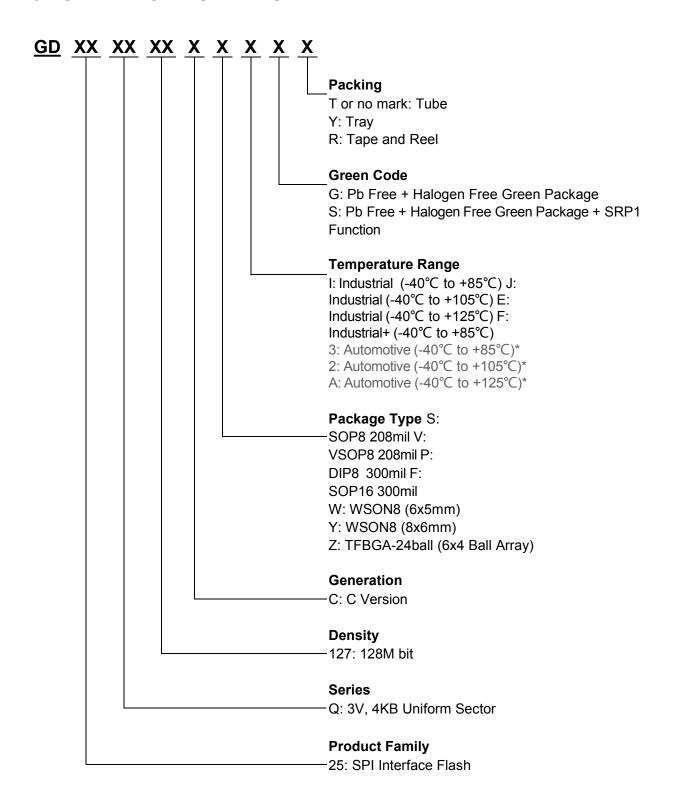


Reset Timing

Symbol	Parameter	Min.	Тур.	Max.	Unit.
tRLRH	Reset Pulse Width	1			μs
tRHSL	Reset High Time Before Read	50			ns
tRB	Reset Recovery Time			12	ms

GD25Q127C

9. ORDERING INFORMATION



^{*} Please contact GigaDevice sales for automotive products.

GD25Q127C

9.1. Valid Part Numbers

Please contact GigaDevice regional sales for the latest product selection and available form factors.

Temperature Range I: Industrial (-40°C to +85°C)

Product Number	Density	Package Type				
GD25Q127CSIG	120Mbit	SOP8 208mil				
GD25Q127CSIS	128Mbit	30P6 20011111				
GD25Q127CVIG	120Mbit	VCOD0 200mil				
GD25Q127CVIS	128Mbit	VSOP8 208mil				
GD25Q127CPIG	120Mbit	DID0 200mil				
GD25Q127CPIS	128Mbit	DIP8 300mil				
GD25Q127CFIG	120Mbit	COD46 200mil				
GD25Q127CFIS	128Mbit	SOP16 300mil				
GD25Q127CWIG	120Mbit	MCONG (SyEmm)				
GD25Q127CWIS	128Mbit	WSON8 (6x5mm)				
GD25Q127CYIG	400N4h:t	\M(CONIQ (0)(Conorm)				
GD25Q127CYIS	128Mbit	WSON8 (8x6mm)				
GD25Q127CZIG	420N4h:t	TEDO A CALCUL (Co.A Dell Armer)				
GD25Q127CZIS	128Mbit	TFBGA-24ball (6x4 Ball Array)				

Temperature Range J: Industrial (-40°C to +105°C)

Product Number	Density	Package Type
GD25Q127CSJG	128Mbit	SOP8 208mil
GD25Q127CSJS	120MUIL	3070 20011111
GD25Q127CVJG	128Mbit	VSOP8 208mil
GD25Q127CVJS	1 ZOIVIDIL	V30P6 20611111
GD25Q127CPJG	400Mb;t	DID0 200mil
GD25Q127CPJS	128Mbit	DIP8 300mil
GD25Q127CFJG	420Mb;t	COD46 200mil
GD25Q127CFJS	128Mbit	SOP16 300mil
GD25Q127CWJG	400Mb;t	MCONG (SyEmm)
GD25Q127CWJS	128Mbit	WSON8 (6x5mm)
GD25Q127CYJG	400145:4	\M(CONIQ (0)(C)====
GD25Q127CYJS	128Mbit	WSON8 (8x6mm)
GD25Q127CZJG	4.00N4h:t	TEDO A CALCULATION A DOLLAR CONTROL
GD25Q127CZJS	128Mbit	TFBGA-24ball (6x4 Ball Array)

GD25Q127C

Temperature Range E: Industrial (-40°C to +125°C)

Product Number	Density	Package Type
GD25Q127CSEG	128Mbit	SOP8 208mil
GD25Q127CSES	120IVIDIL	30P6 206IIII
GD25Q127CVEG	420Mb;t	VCOD0 200mil
GD25Q127CVES	128Mbit	VSOP8 208mil
GD25Q127CPEG	120Mbit	DIP8 300mil
GD25Q127CPES	128Mbit	DIP6 300IIII
GD25Q127CFEG	120Mbit	SOP16 300mil
GD25Q127CFES	128Mbit	SOP 16 30011111
GD25Q127CWEG	120Mbit	MCONO (SyEmm)
GD25Q127CWES	128Mbit	WSON8 (6x5mm)
GD25Q127CYEG	120Mbit	M/SONIO (Qy6mm)
GD25Q127CYES	128Mbit	WSON8 (8x6mm)
GD25Q127CZEG	420Mb;t	TEDCA 24boll (Cv.4 Doll Arrow)
GD25Q127CZES	128Mbit	TFBGA-24ball (6x4 Ball Array)

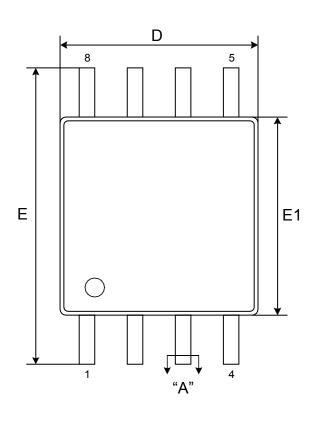
Temperature Range F: Industrial+ (-40°C to +85°C)

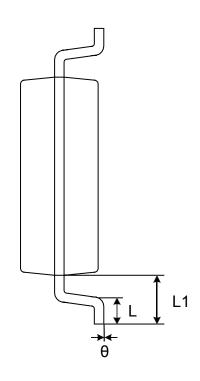
Product Number	Density	Package Type
GD25Q127CSFG	128Mbit	SOP8 208mil
GD25Q127CSFS	120IVIDIL	SOP6 20611III
GD25Q127CVFG	100Mbit	VCOD0 200mil
GD25Q127CVFS	128Mbit	VSOP8 208mil
GD25Q127CPFG	100Mbit	DID0 200mil
GD25Q127CPFS	128Mbit	DIP8 300mil
GD25Q127CFFG	100Mbit	COD46 200mil
GD25Q127CFFS	128Mbit	SOP16 300mil
GD25Q127CWFG	120Mbit	MSON9 (SyEmm)
GD25Q127CWFS	128Mbit	WSON8 (6x5mm)
GD25Q127CYFG	400Mb;4	\\(CO\\\\\(C\\\\\\\\\\\\\\\\\\\\\\\\\\\
GD25Q127CYFS	128Mbit	WSON8 (8x6mm)
GD25Q127CZFG	4000454	TEDO A CALCUL (CAA Dall Access)
GD25Q127CZFS	128Mbit	TFBGA-24ball (6x4 Ball Array)

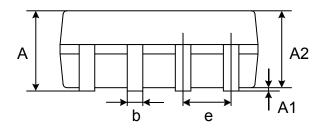
GD25Q127C

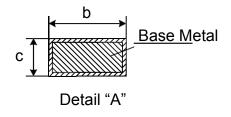
10. PACKAGE INFORMATION

10.1. Package SOP8 208MIL









Dimensions

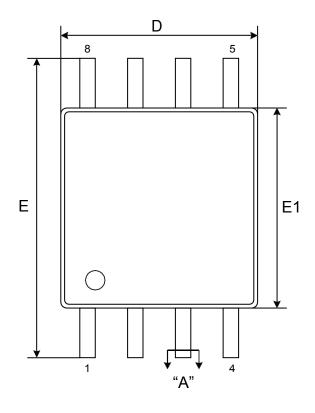
Symbol		Α	A1	A2	b	С	D	Е	E1	е	ı	L1	θ
U	Unit		***	,				_			_		
	Min	-	0.05	1.70	0.31	0.15	5.13	7.70	5.18		0.50		0°
mm	Nom	-	0.15	1.80	0.41	0.20	5.23	7.90	5.28	1.27	-	1.31	-
	Max	2.16	0.25	1.90	0.51	0.25	5.33	8.10	5.38		0.85		8°

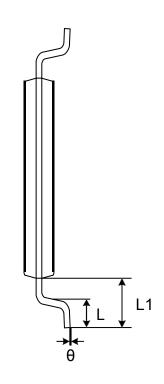
- 1. Both the package length and width do not include the mold flash.
- 2. Seating plane: Max. 0.1mm.

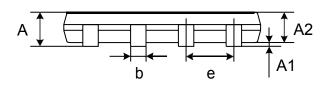


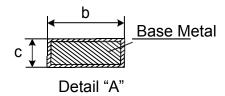
GD25Q127C

10.2. Package VSOP8 208MIL









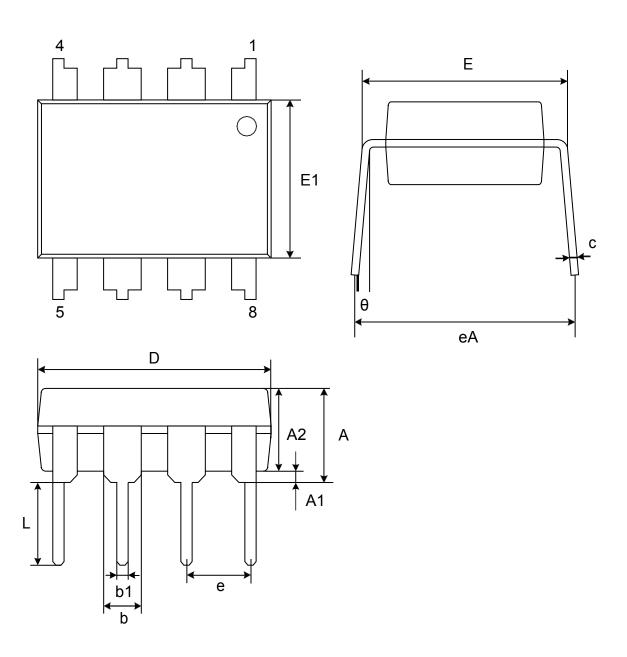
Dimensions

Symbol Unit		۸	A1	A2	b	С	D	E	E1			L1	θ
		A	^1	AZ	"			_	E1	е	_ L	L.	
	Min	-	0.05	0.75	0.35	0.09	5.18	7.70	5.18		0.50		0°
mm	Nom	-	0.10	0.80	0.42	0.15	5.28	7.90	5.28	1.27	-	1.31	-
	Max	1.00	0.15	0.85	0.50	0.20	5.38	8.10	5.38		0.80		10°

- 1. Both the package length and width include the mold flash.
- 2. Seating plane: Max. 0.1mm.

GD25Q127C

10.3. Package DIP8 300MIL



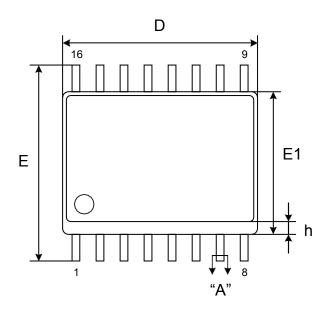
Dimensions

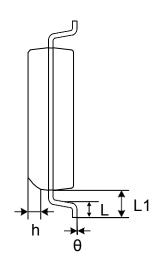
Sy	mbol		A 4	A2	L	h.1	С	D	E	E1			- ^	θ
ι	Jnit	A	A 1	AZ	b	b1		U	_	E1	е	_	eA	0
	Min	-	0.38	3.00	1.14	0.36	0.20	9.02	7.62	6.10		2.92	8.45	0°
mm	Nom	-	-	3.30	1.52	0.46	0.25	9.27	7.87	6.35	2.54	3.30	8.90	-
	Max	3.88	-	3.50	1.78	0.56	0.35	9.59	8.26	6.60		3.81	9.35	11°

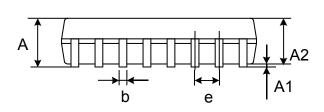
Note: Both the package length and width do not include the mold flash.

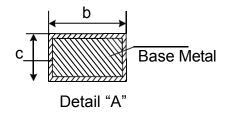
GD25Q127C

10.4. Package SOP16 300MIL









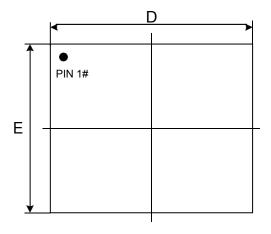
Dimensions

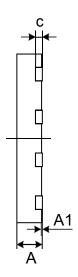
Syı	mbol	Δ.	A1	A2	b		D	E	E1			L1	h	θ
u	Unit		AI	AZ	"	С		-		е	_	LI	h	U
	Min	-	0.10	2.05	0.31	0.10	10.20	10.10	7.40		0.40		0.25	0
mm	Nom	-	0.20	-	0.41	0.25	10.30	10.30	7.50	1.27	-	1.40	-	-
	Max	2.65	0.30	2.55	0.51	0.33	10.40	10.50	7.60		1.27		0.75	8

- 1. Both the package length and width do not include the mold flash.
- 2. Seating plane: Max. 0.1mm.

GD25Q127C

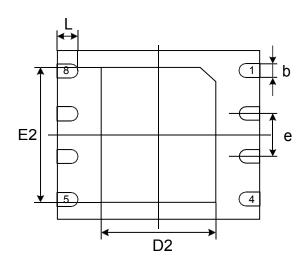
Package WSON8 (6*5mm) 10.5.





Top View

Side View



Bottom View

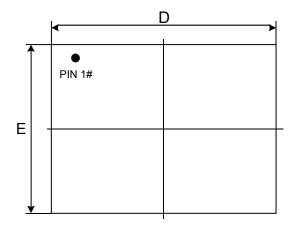
Dimensions

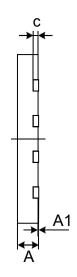
Symbol			A1		b	D	D2	_	E2		
U	Jnit	A	AI	С	b		D2	E	E2	е	L
	Min	0.70	0.00	0.180	0.35	5.90	3.30	4.90	3.90		0.50
mm	Nom	0.75	0.02	0.203	0.40	6.00	3.40	5.00	4.00	1.27	0.60
	Max	0.80	0.05	0.250	0.50	6.10	3.50	5.10	4.10		0.75

- 1. Both the package length and width do not include the mold flash.
- 2. The exposed metal pad area on the bottom of the package is floating.
- 3. Coplanarity ≤0.08mm. Package edge tolerance≤0.10mm.
- 4. The lead shape may be of little difference according to different package lead frames. These lead shapes are compatible with each other.

GD25Q127C

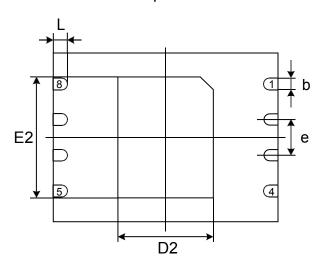
10.6. Package WSON8 (8*6mm)





Top View

Side View



Bottom View

Dimensions

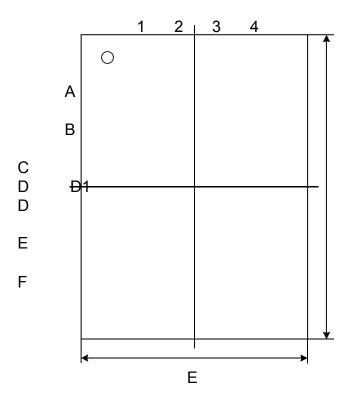
	mbol Jnit	A	A 1	С	b	D	D2	E	E2	е	L
	Min	0.70	0.00	0.180	0.35	7.90	3.30	5.90	4.20	1.27	0.45
mm	Nom	0.75	0.02	0.203	0.40	8.00	3.40	6.00	4.30		0.50
	Max	0.80	0.05	0.250	0.45	8.10	3.50	6.10	4.40		0.55

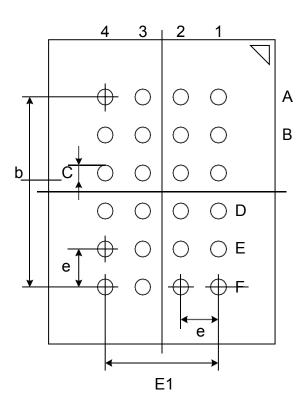
- 1. Both the package length and width do not include the mold flash.
- 2. The exposed metal pad area on the bottom of the package is floating.
- 3. Coplanarity \leq 0.08mm. Package edge tolerance \leq 0.10mm.
- 4. The lead shape may be of little difference according to different package lead frames. These lead shapes are compatible with each other.

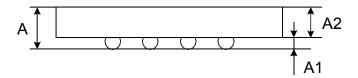


GD25Q127C

10.7. Package TFBGA-24BALL (6*4 ball array)







Dimensions

	Symbol Unit		Α	A1	A2	b	E	E1	D	D1	е
		Min	-	0.25	0.75	0.35	5.90		7.90		
	mm	Nom	-	0.30	0.80	0.40	6.00	3.00	8.00	5.00	1.00
		Max	1.20	0.35	0.85	0.45	6.10		8.10		

Note: Both the package length and width do not include the mold flash.



GD25Q127C

11. REVISION HISTORY

Version No	Description	Page	Date				
1.0	Initial Release	All	2016-03-17				
1.1	Modify SFDP table	P40-43	2016-05-31				
	Modify TFBGA-24Ball (6*4 ball array)	P60					
	Delete Data Retention and endurance	P4					
1.2	Modify POWER-ON TIMING: VWI Min 1V Change to 1.5V.	P44	2016-07-20				
	Add Valid Part Numbers	P53					
	Modify Features: Add Allows XIP(execute in place)operation	P4					
1.2	Update Table7.5. Parameter Table (1): GigaDevice Flash	P43	2016 09 26				
1.3	Parameter Tables		2016-08-26				
1.4	Modify Package WSON8 8x6mm	P59	2016-12-15				
	Modify SRP1, SRP0 bits Notes	P13					
4.5	Modify ORDERING INFORMATION	P51	2047.02.22				
1.5	Update WSON8(6*5mm)	P57	2017-02-23				
	Update WOSN8(8*6mm)	P58					
1.6	Update ORDERING INFORMATION	P51	2017-03-08				
	Add Packing Type of "T or no mark: Tube" in the Ordering	P52					
1.7	Information						
	Update the Package descriptions	P54-56, 58-60					
	Modify VCC from "-0.6 to 4.0" to "-0.6 to 4.2"	P44					
	Add Icc8. The max value of Icc8 is 25mA for Normal Mode and	P46, 47					
1.8	15mA for Low Power Mode		2017-10-23				
1.0	Delete tRST_R and tRST_P	P48, 50	2017-10-23				
	Add tRST. The max of tRST is 30us for Normal Mode and 50us	P48, 50					
	for Low Power Mode						
	Add 4BH command	P39					
	Modify tVSL min value from 5ms to 2.5ms	P45					
	Add tRS, min = 100us	P53, 55					
	Modify tRB from 5/60us to 12ms	P49					
	Update the description of all the packages	P58-64					
	Normal Mode -40°C~85°C :						
	Modify Icc4-8 max. value from 25mA to 27mA	P47					
1.9	Modify tPP typ. value from 0.6s to 0.5s	P50	2018-07-11				
	Modify tBE1 from 0.2s~1s to 0.16s~0.8s	P50					
	Modify tCE from typ. value from 60s to 50s	P50					
	Low Power Mode -40°C~85°C :						
	Modify Deep Power-Down Current from 0.1~1uA to 1~5uA	P48					
	Modify Icc3@104MHz max value from 18mA to 20mA	P48					
	Modify Icc3@80MHz max value from 15mA to 18mA						
	Modify Icc4-8 max value from 15mA to 25mA	P48	1				



	Modify Figure 32. Program Security Registers command	P37	
	Sequence Diagram		
2.0	Add DC/AC characteristics @-40°C~105°C	P49-50/P57-60	2018-8-2
	Add DC/AC characteristics @-40°C~125°C	P51-52/P61-64	
	Modify Ordering Information	P67	
2.1	Modify AC characteristics@Fc,fc1,fc2,fR	P53,55,57,59,61,63	2018-8-21

GD25Q127C

Important Notice

This document is the property of GigaDevice Semiconductor (Beijing) Inc. and its subsidiaries (the "Company"). This document, including any product of the Company described in this document (the "Product"), is owned by the Company under the intellectual property laws and treaties of the People's Republic of China and other jurisdictions worldwide. The Company reserves all rights under such laws and treaties and does not grant any license under its patents, copyrights, trademarks, or other intellectual property rights. The names and brands of third party referred thereto (if any) are the property of their respective owner and referred to for identification purposes only.

The Company makes no warranty of any kind, express or implied, with regard to this document or any Product, including, but not limited to, the implied warranties of merchantability and fitness for a particular purpose. The Company does not assume any liability arising out of the application or use of any Product described in this document. Any information provided in this document is provided only for reference purposes. It is the responsibility of the user of this document to properly design, program, and test the functionality and safety of any application made of this information and any resulting product. Except for customized products which has been expressly identified in the applicable agreement, the Products are designed, developed, and/or manufactured for ordinary business, industrial, personal, and/or household applications only. The Products are not designed, intended, or authorized for use as components in systems designed or intended for the operation of weapons, weapons systems, nuclear installations, atomic energy control instruments, combustion control instruments, airplane or spaceship instruments, traffic signal instruments, life-support devices or systems, other medical devices or systems (including resuscitation equipment and surgical implants), pollution control or hazardous substances management, or other uses where the failure of the device or Product could cause personal injury, death, property or environmental damage ("Unintended Uses"). Customers shall take any and all actions to ensure using and selling the Products in accordance with the applicable laws and regulations. The Company is not liable, in whole or in part, and customers shall and hereby do release the Company as well as it's suppliers and/or distributors from any claim, damage, or other liability arising from or related to all Unintended Uses of the Products. Customers shall indemnify and hold the Company as well as it's suppliers and/or distributors harmless from and against all claims, costs, damages, and other liabilities, including claims for personal injury or death, arising from or related to any Unintended Uses of the Products.

Information in this document is provided solely in connection with the Products. The Company reserves the right to make changes, corrections, modifications or improvements to this document and the Products and services described herein at any time, without notice.